

Introduction to Scientific Computing Languages

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Deutsche
Forschungsgemeinschaft

DFG

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- A set of **instructions and constructs** for communicating with a computing device.
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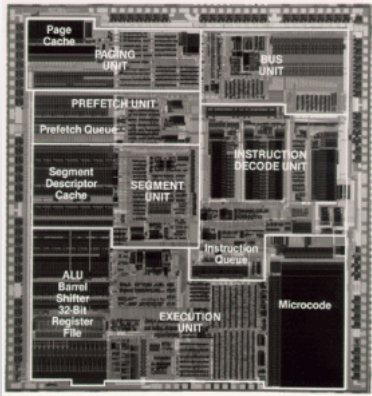
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- Examples: Basic, Pascal, Cobol, Fortran, C, C++, Lisp, Prolog, SQL, Java, Perl, Python, Ruby, ...

“Computing device”?

sequential processors, embedded processors, ...,
parallel computers, supercomputers.

Processor's Components

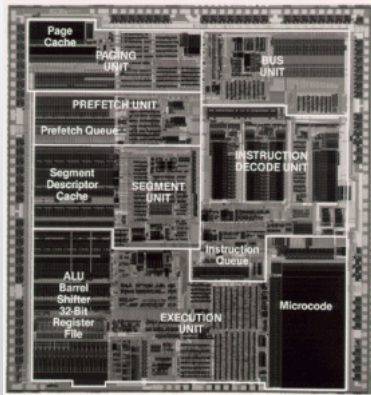
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Arithmetic Logic Unit (ALU) (control signals, inputs, outputs), Floating Point Unit (FPU), Prefetching Unit, Registers, . . .

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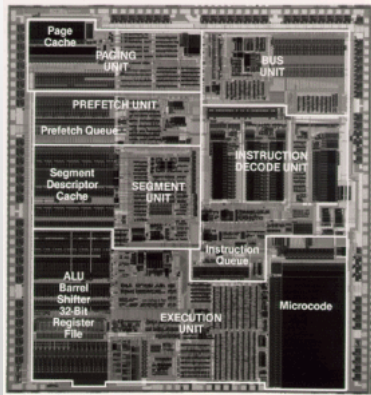


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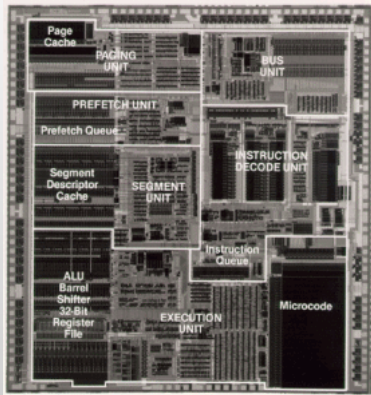


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- Only **Assembly** operates on components: Low-level language.

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- Languages let the users specify how to use these components.
- Only **Assembly** operates on components: Low-level language.
- High-level languages only specify the computations to be performed.
- A **compiler** and/or an **interpreter** translates high-level programs into a sequence of component actions.

Arithmetic Logic Unit (ALU) (control signals, inputs, outputs), Floating Point Unit (FPU), Prefetching Unit, Registers, . . .

Assembly

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- **Assembler** translates assembly into machine code. Executable.
- Assembly consists of mnemonic codes.
Machine code: only numbers.
- Translation Assembly \leftrightarrow machine code is almost 1-1.
This is not true for high-level languages.
- Assembler is hardware-specific. Control over chips' components.

Assembly

Example

```
        .text
        .globl poly

poly:
        li.s  $f0, 0.0           # y = 0, running & return result
        mtc1  $6  $f12           # x, move to float register

Loop:
        mul.s $f14, $f12, $f0    # compute (x * y)
        mul   $2, $5, 4          # $5 = i, compute address of a[i]
        addu  $3, $2, $4         # a + (i*4)
        l.s   $f16, 0($3)       # a[i], load coefficient
        add.s $f0, $f16, $f14    # y = a[i] + (x*y)
        addi  $5, $5, -1        # decrease i

        slt   $2, $5, $0        # $2 = 1 if i < 0
        beq   $2, $0, Loop      # goto Loop if i >= 0

Exit:
        j     $31
```

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Evaluate the value of a polynomial using Horner's algorithm.
$f = a[0] + a[1] * x + a[2] * x^2 + \dots + a[n] * x^n$

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'70s	Pascal('70), C ('72), Prolog('72), SQL('78), Matlab ('78)
'80s	C++('83), Perl('87), Mathematica ('87)
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Oldest programming language?

Plankalkül (1940s). For the Z1 computer, by Konrad Zuse.

WEB

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- Examples: C, Fortran.

Interpreted Languages

- The instructions are parsed and executed in real time by an **interpreter**.
- No generated code. The interpreter is always needed.
- **Ease!**
- Examples: Matlab, Mathematica, Python.

Computer Programs

Program:

sequence of instructions expressing the operations to be performed on a target computing platform.

- Each program \mathcal{P} has a meaning. It implements a function.
 $\{\text{Initial State}\} \quad \mathcal{P} \quad \{\text{Final State}\}.$

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 $[[\]] =$ Semantics operator. Operational, Denotational, Axiomatic.
Out of the scope of this class.
- Generally, we want \mathcal{P} to compute $f(i)$, with $i \in I$.
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- A program \mathcal{P} is **correct** if $\forall i \in I, \mathcal{P}(i) \equiv f(i)$.
- Surprisingly... when working with floating point numbers, correctness is not enough!

Subroutines

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result := routine_name( arguments )
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result := routine_name( arguments )
```

- BUT! One difference: side-effects.
Many languages allow subroutines to have side-effects. The routine alters the state of the system even after its completion.

Side Effects

$\{ (res = \dots) \wedge State \}$

`res := routine_name(args);`

$\{ (res = \dots) \wedge State' \}$

- If $(State = State') \rightarrow$ no side-effects.
- Most languages allow constructs with side-effects.
- Print statements; iterative constructs; ...

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- Structure:

```
routine_name( args )  
    //  
    body  
    //  
    return( value )
```

args, body and value are optional, depending on the language.

Questions about Subroutines

<code>routine_name_1(args_1)</code>	<code>routine_name_2(args_2)</code>
<code>//</code>	<code>//</code>
<code>body_1</code>	<code>body_2</code>
<code>//</code>	<code>//</code>
<code>return(value2)</code>	<code>return(value_2)</code>

- Can `body_1` include a call to `routine_name_1`?

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routine_name_1(args_1)    routine_name_2(args_2)
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 - Mutual recursion.

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Recursion \equiv iteration!

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It provides building blocks to be used when writing a program.
- BLAS LAPACK PETSc MPI Pthreads ...
 LINPACK
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- Libraries can be written in one or more languages.
Can they be accessed from a program written in a different language?

Imperative vs. Functional Languages

Imperative Languages

- Concept of **Variables** and **State**.
- Program is an ordered sequence of commands and **assignments**.
- Commands modify state. Side-effects.
- C, C++, Fortran, Java, Python, Matlab, ...

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Functional Languages

- No variables or assignments.
- Program consists of **Functions** and **Recursion**.
- No side-effects!
- Subset of Declarative Languages.
- Lisp, APL, ADA, Haskell, Mathematica, Clojure, F# ...

Scope

```
Program A;  
  Var I:Integer;  
      K:Char;  
      R:Real;  
  
  Procedure B;  
    Var K:Real;  
        L:Integer;  
  
    Procedure C;  
      Var M:Real;  
      Begin  
        // Body #1  
      End;  
    Begin  
      // Body #2  
    End;  
  Begin  
    // Body #3  
  End;
```

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- Which variables (of which type) are defined in Body #1?

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I:Integer, R:Real, K:Real, L:Integer,  
M:Real
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- Where is K used as Real?

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Body #1 and Body #2

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M:Real
```

- Where is K used as Real?

Body #1 and Body #2

- Can L be referenced in Body #2? Body #3?

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        // Body #1  
      End;  
    Begin  
      // Body #2  
    End;  
  Begin  
    // Body #3  
  End;
```

- Which variables (of which type) are defined in Body #1?

I:Integer, R:Real, K:Real, L:Integer,
M:Real

- Where is K used as Real?

Body #1 and Body #2

- Can L be referenced in Body #2? Body #3?

Body #2: yes; Body #3: no

Scope (2)

```
program main
var y: Real;
  procedure compute()
    var x : Integer;
    procedure initialize()
      var y: Integer;
      var z: Real;
      begin {initialize}
        // Body #1
      end {initialize}

      procedure transform()
        var x: Real;
        begin {transform}
          // Body #2
        end {transform}
      begin {compute}
        // Body #3
      end {compute}
    begin {main}
      // Main body
    end {main}
```

Scope (2)

```
program main
var y: Real;
  procedure compute()
    var x : Integer;
    procedure initialize()
      var y: Integer;
      var z: Real;
      begin {initialize}
        // Body #1
      end {initialize}

      procedure transform()
        var x: Real;
        begin {transform}
          // Body #2
        end {transform}
      begin {compute}
        // Body #3
      end {compute}
    begin {main}
      // Main body
    end {main}
```

- What is the scope of the variable `x` declared in the procedure `compute`?

Scope (2)

```
program main
var y: Real;
  procedure compute()
    var x : Integer;
    procedure initialize()
      var y: Integer;
      var z: Real;
      begin {initialize}
        // Body #1
      end {initialize}

      procedure transform()
        var x: Real;
        begin {transform}
          // Body #2
        end {transform}
      begin {compute}
        // Body #3
      end {compute}
    begin {main}
      // Main body
    end {main}
```

- What is the scope of the variable `x` declared in the procedure `compute`?

Body #1 and Body #3

Scope (2)

```
program main
var y: Real;
  procedure compute()
    var x : Integer;
    procedure initialize()
      var y: Integer;
      var z: Real;
      begin {initialize}
        // Body #1
      end {initialize}

      procedure transform()
        var x: Real;
        begin {transform}
          // Body #2
        end {transform}
      begin {compute}
        // Body #3
      end {compute}
    begin {main}
      // Main body
    end {main}
```

- What is the scope of the variable `x` declared in the procedure `compute`?

Body #1 and Body #3

- What is the environment for the procedure `transform`?

Scope (2)

```
program main
var y: Real;
  procedure compute()
    var x : Integer;
    procedure initialize()
      var y: Integer;
      var z: Real;
      begin {initialize}
        // Body #1
      end {initialize}

      procedure transform()
        var x: Real;
        begin {transform}
          // Body #2
        end {transform}
      begin {compute}
        // Body #3
      end {compute}
    begin {main}
      // Main body
    end {main}
```

- What is the scope of the variable `x` declared in the procedure `compute`?

Body #1 and Body #3

- What is the environment for the procedure `transform`?

`y:Real` and `x:Real`