

FROM PROBLEM TO SOLUTION IN ONE CL1CK

Prof. Paolo Bientinesi

pauldj@cs.umu.se



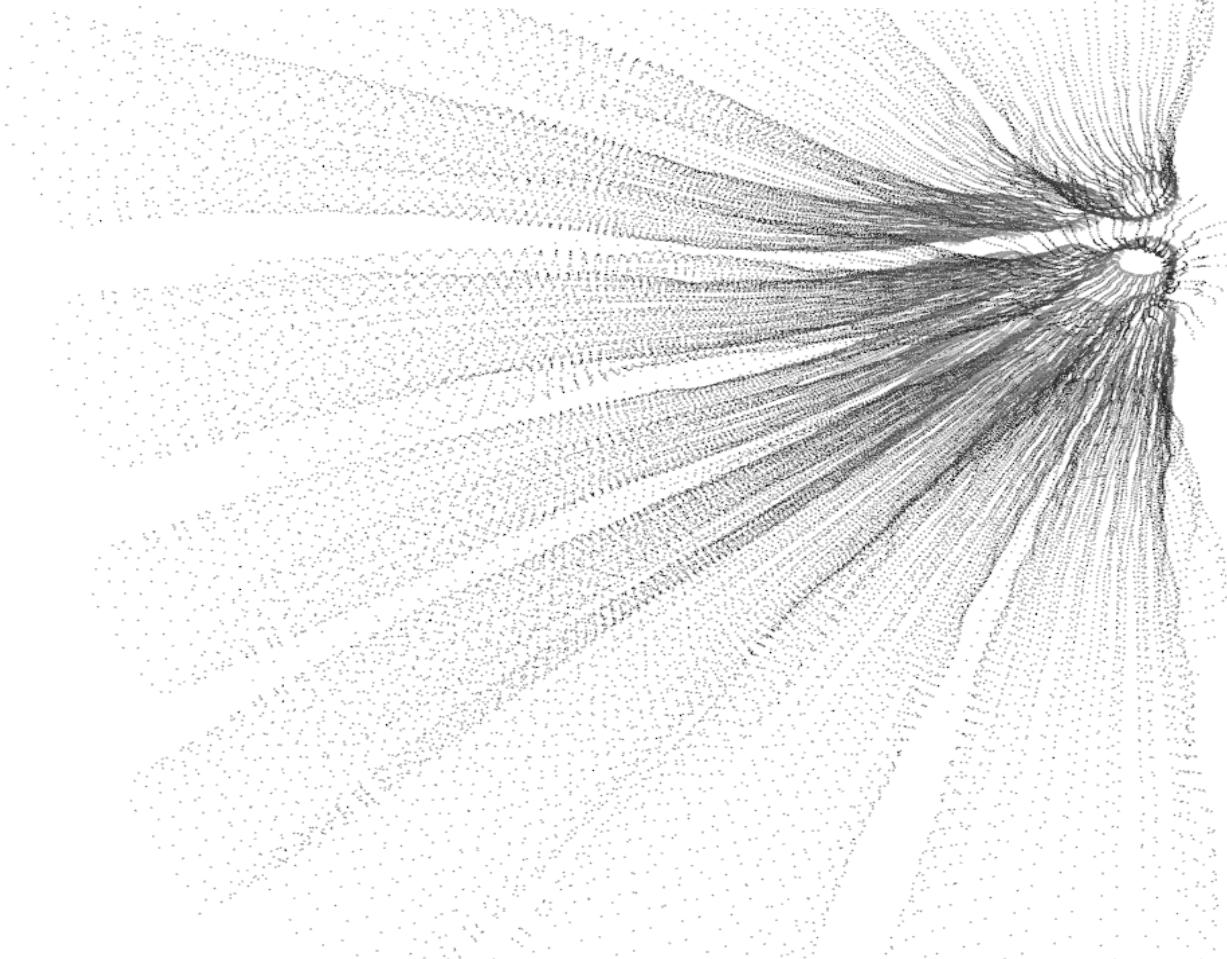
UMEÅ UNIVERSITY

The World of Computing

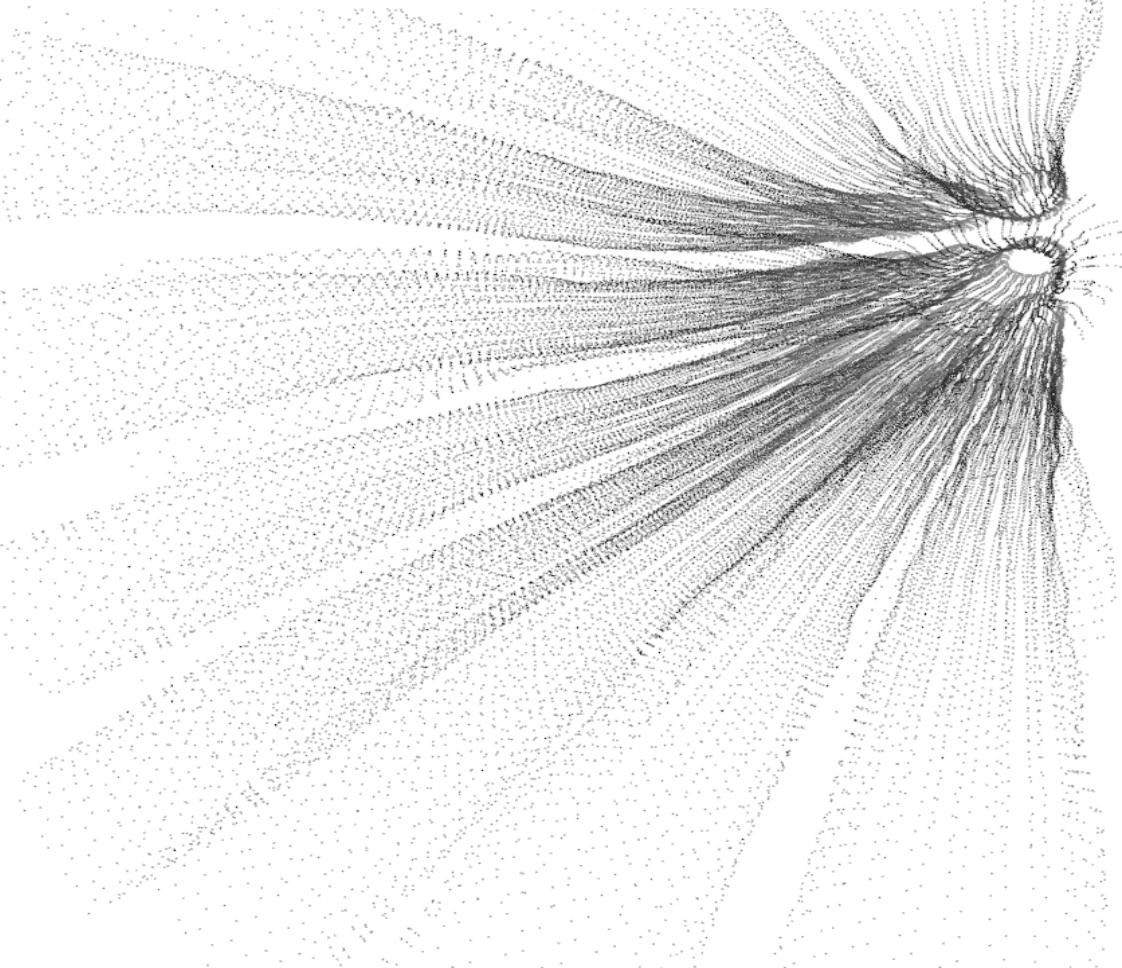
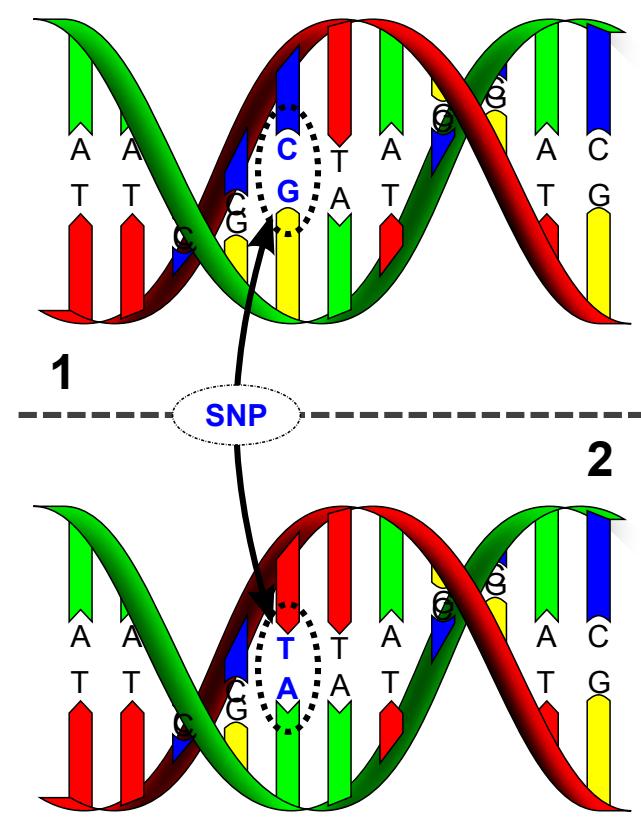


UMEÅ UNIVERSITY

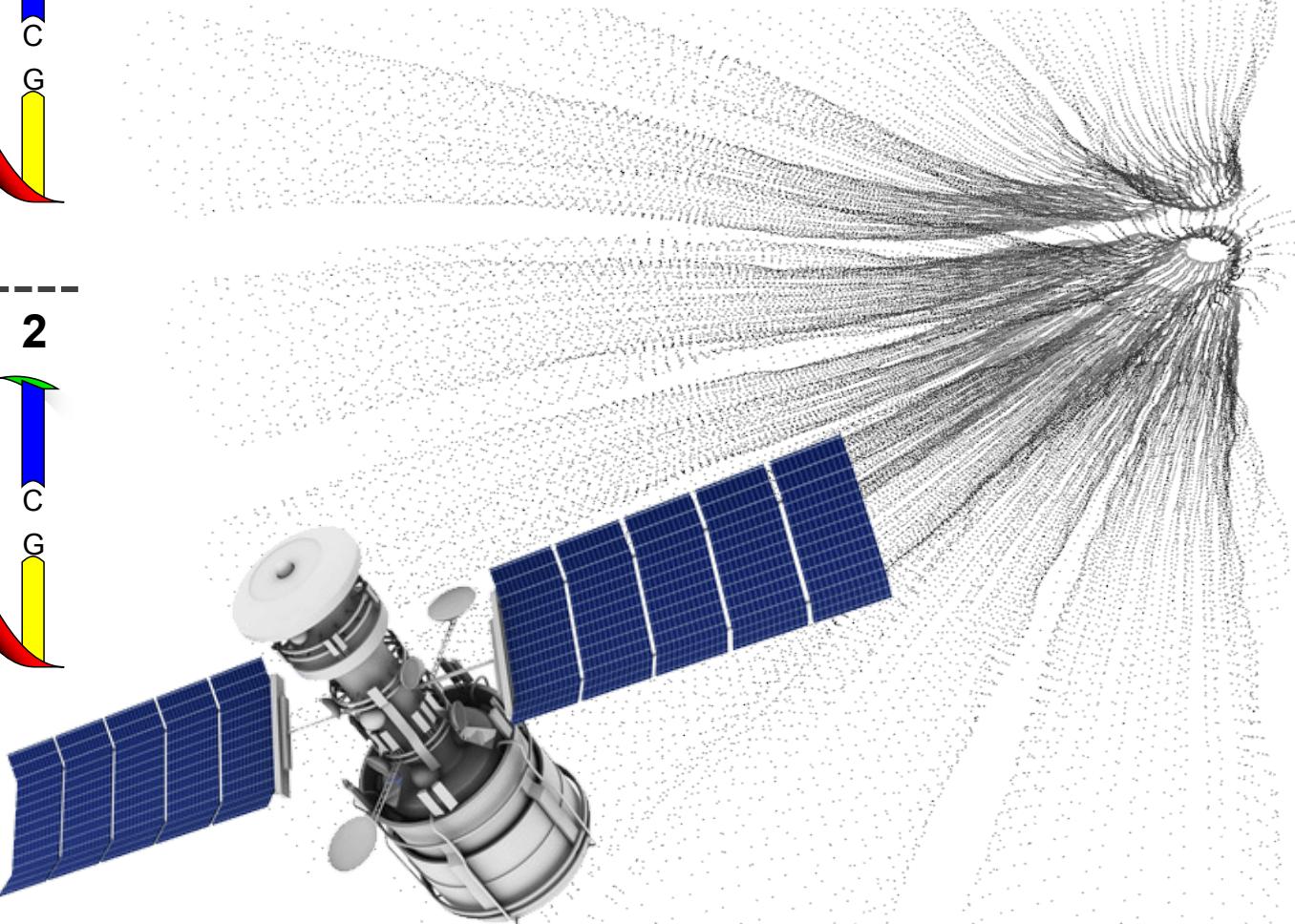
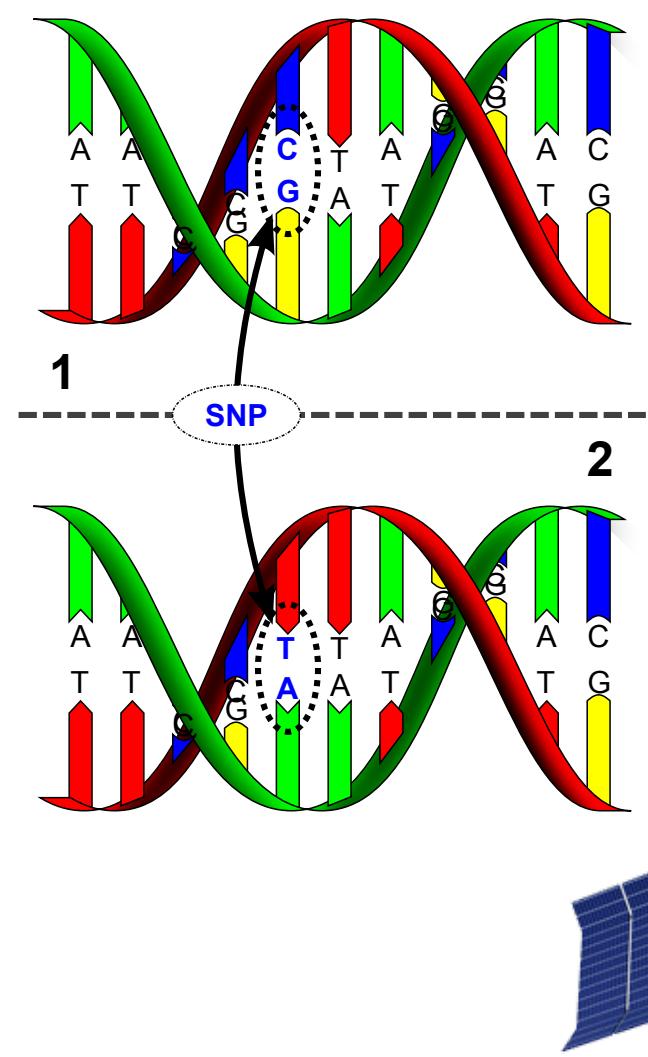
The World of Computing



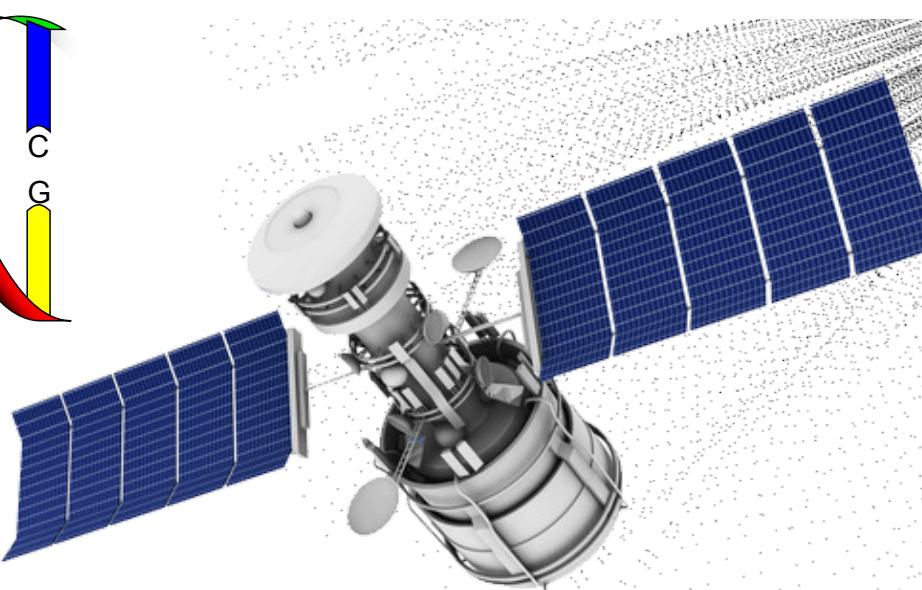
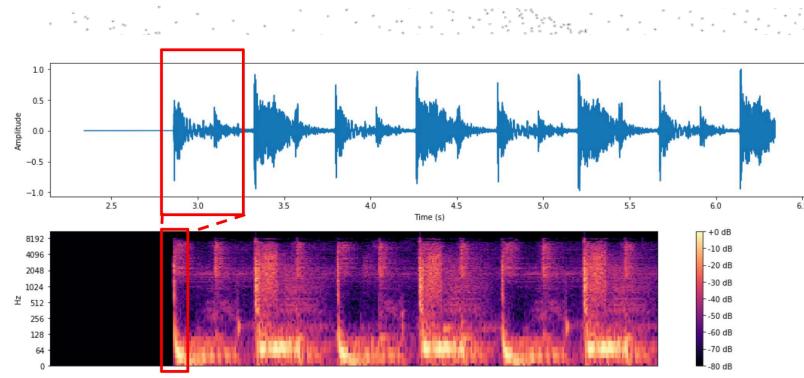
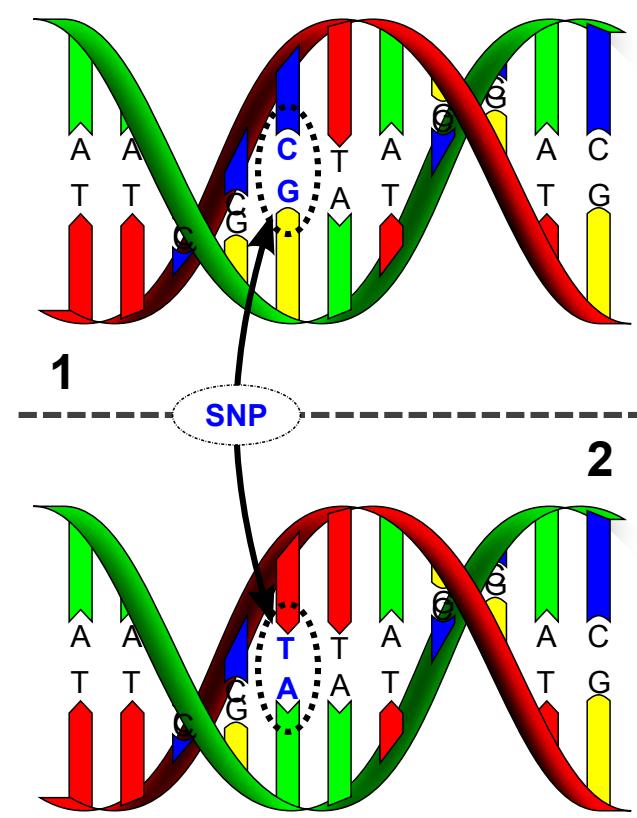
The World of Computing



The World of Computing



The World of Computing



Countries



Middle Earth
by Cave-Geek (Kfir M.)

$$\mathbf{y} = X\beta + Z\mathbf{u} + \epsilon$$

$$\min_{\mathbf{x}} \|A\mathbf{x} - \mathbf{b}\|^2 + \|\Gamma\mathbf{x}\|^2$$

$$i\hbar \frac{\partial}{\partial t} \Psi(\mathbf{r}, t) = \left[\frac{-2\hbar}{2\mu} \nabla^2 + V(\mathbf{r}, t) \right] \Psi(\mathbf{r}, t)$$

$$V_{LJ} = 4\varepsilon \left[\left(\frac{\sigma}{r} \right)^{12} - \left(\frac{\sigma}{r} \right)^6 \right]$$

$$\frac{\partial}{\partial t} (\rho \mathbf{u}) + \nabla \cdot (\rho \mathbf{u} \otimes \mathbf{u}) = -\nabla \cdot p \mathbf{I} + \nabla \tau + \rho \mathbf{g}$$

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\mathbf{u} + \boldsymbol{\epsilon}$$

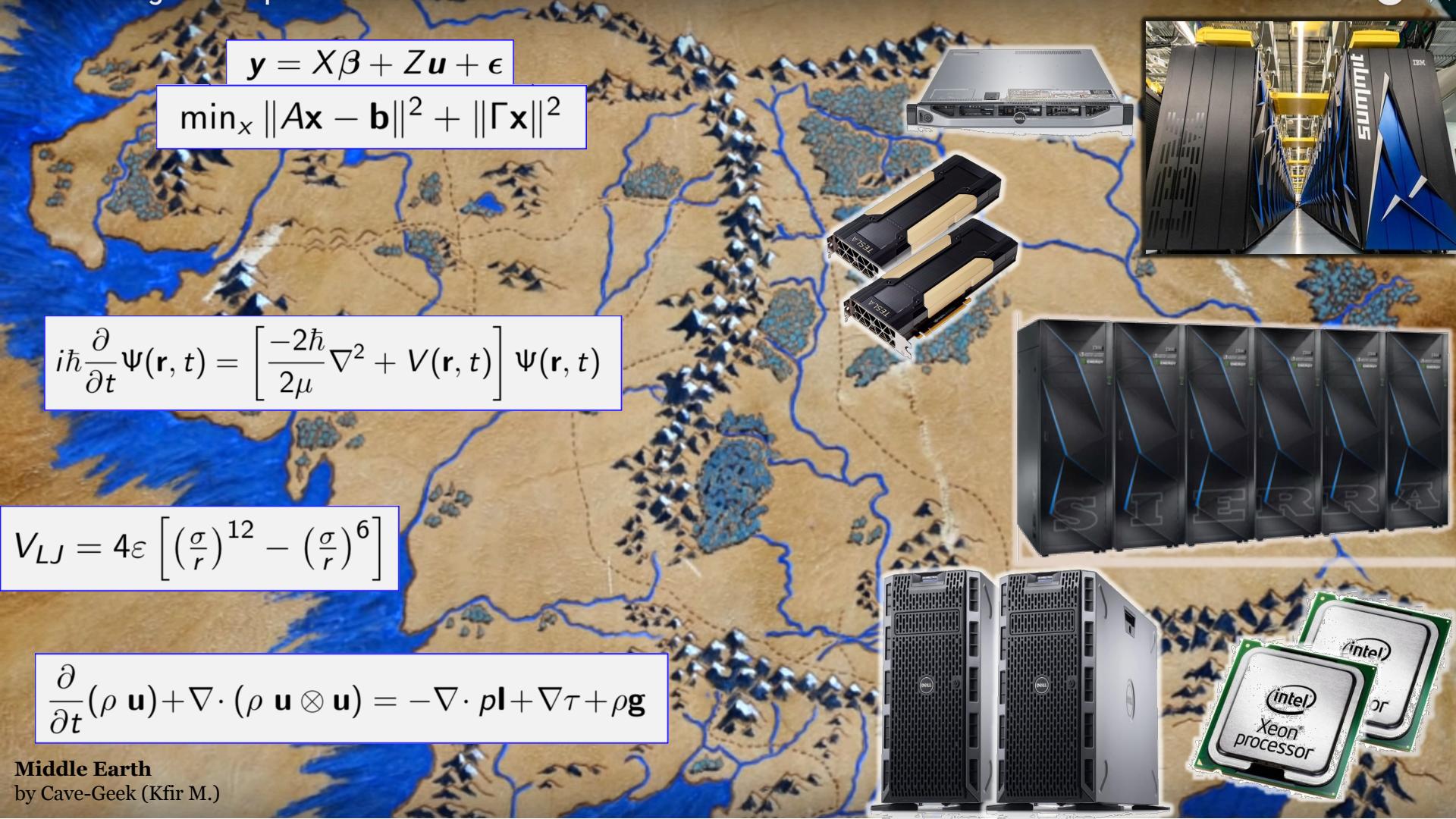
$$\min_{\mathbf{x}} \|A\mathbf{x} - \mathbf{b}\|^2 + \|\Gamma\mathbf{x}\|^2$$

$$i\hbar\frac{\partial}{\partial t}\Psi(\mathbf{r},t)=\left[\frac{-2\hbar}{2\mu}\nabla^2+V(\mathbf{r},t)\right]\Psi(\mathbf{r},t)$$

$$V_{LJ}=4\varepsilon\left[\left(\frac{\sigma}{r}\right)^{12}-\left(\frac{\sigma}{r}\right)^6\right]$$

$$\frac{\partial}{\partial t}(\rho \mathbf{u}) + \nabla \cdot (\rho \mathbf{u} \otimes \mathbf{u}) = -\nabla \cdot p\mathbf{I} + \nabla \tau + \rho \mathbf{g}$$

Middle Earth
by Cave-Geek (Kfir M.)



$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\mathbf{u} + \boldsymbol{\epsilon}$$

$$\min_{\mathbf{x}} \|\mathbf{A}\mathbf{x} - \mathbf{b}\|^2 + \|\boldsymbol{\Gamma}\mathbf{x}\|^2$$

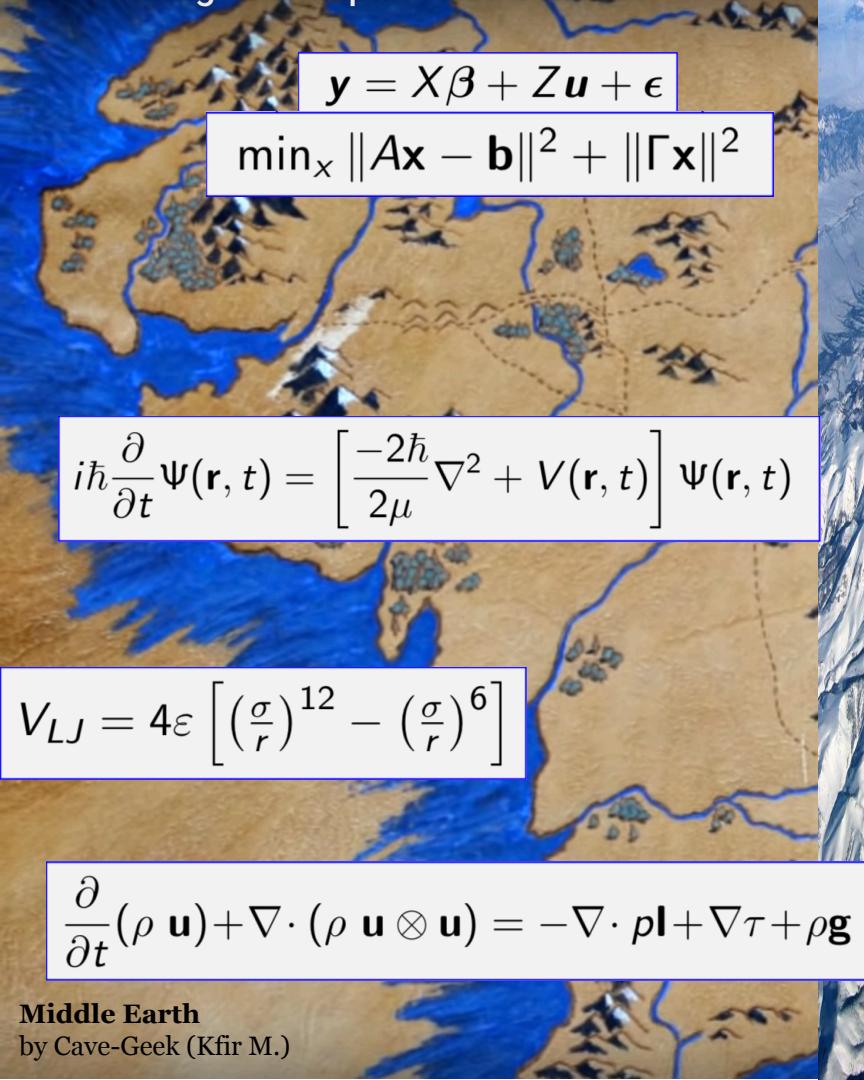
$$i\hbar \frac{\partial}{\partial t} \Psi(\mathbf{r}, t) = \left[\frac{-2\hbar}{2\mu} \nabla^2 + V(\mathbf{r}, t) \right] \Psi(\mathbf{r}, t)$$

$$V_{LJ} = 4\varepsilon \left[\left(\frac{\sigma}{r} \right)^{12} - \left(\frac{\sigma}{r} \right)^6 \right]$$

$$\frac{\partial}{\partial t} (\rho \mathbf{u}) + \nabla \cdot (\rho \mathbf{u} \otimes \mathbf{u}) = -\nabla \cdot p \mathbf{I} + \nabla \tau + \rho \mathbf{g}$$

Middle Earth
by Cave-Geek (Kfir M.)




$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\mathbf{u} + \boldsymbol{\epsilon}$$

$$\min_{\mathbf{x}} \|\mathbf{Ax} - \mathbf{b}\|^2 + \|\Gamma \mathbf{x}\|^2$$

$$i\hbar \frac{\partial}{\partial t} \Psi(\mathbf{r}, t) = \left[\frac{-2\hbar}{2\mu} \nabla^2 + V(\mathbf{r}, t) \right] \Psi(\mathbf{r}, t)$$

$$V_{LJ} = 4\varepsilon \left[\left(\frac{\sigma}{r} \right)^{12} - \left(\frac{\sigma}{r} \right)^6 \right]$$

$$\frac{\partial}{\partial t} (\rho \mathbf{u}) + \nabla \cdot (\rho \mathbf{u} \otimes \mathbf{u}) = -\nabla \cdot p \mathbf{I} + \nabla \tau + \rho \mathbf{g}$$

Middle Earth
by Cave-Geek (Kfir M.)



$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\mathbf{u} + \boldsymbol{\epsilon}$$

$$\min_{\mathbf{x}} \|\mathbf{A}\mathbf{x} - \mathbf{b}\|^2 + \|\boldsymbol{\Gamma}\mathbf{x}\|^2$$

$$i\hbar\frac{\partial}{\partial t}\Psi(\mathbf{r},t)=\left[\frac{-2\hbar}{2\mu}\nabla^2+V(\mathbf{r},t)\right]\Psi(\mathbf{r},t)$$

$$V_{LJ} = 4\varepsilon \left[\left(\frac{\sigma}{r} \right)^{12} - \left(\frac{\sigma}{r} \right)^6 \right]$$

$$\frac{\partial}{\partial t}(\rho \mathbf{u}) + \nabla \cdot (\rho \mathbf{u} \otimes \mathbf{u}) = -\nabla \cdot p\mathbf{I} + \nabla \tau + \rho \mathbf{g}$$

Middle Earth
by Cave-Geek (Kfir M.)



$$y = X\beta + Zu + \epsilon$$



Middle Earth
by Cave-Geek (Kfir M.)













Programmability



UMEÅ UNIVERSITY

Programmability

1960's

- computers very difficult to program
- programs easy to optimize

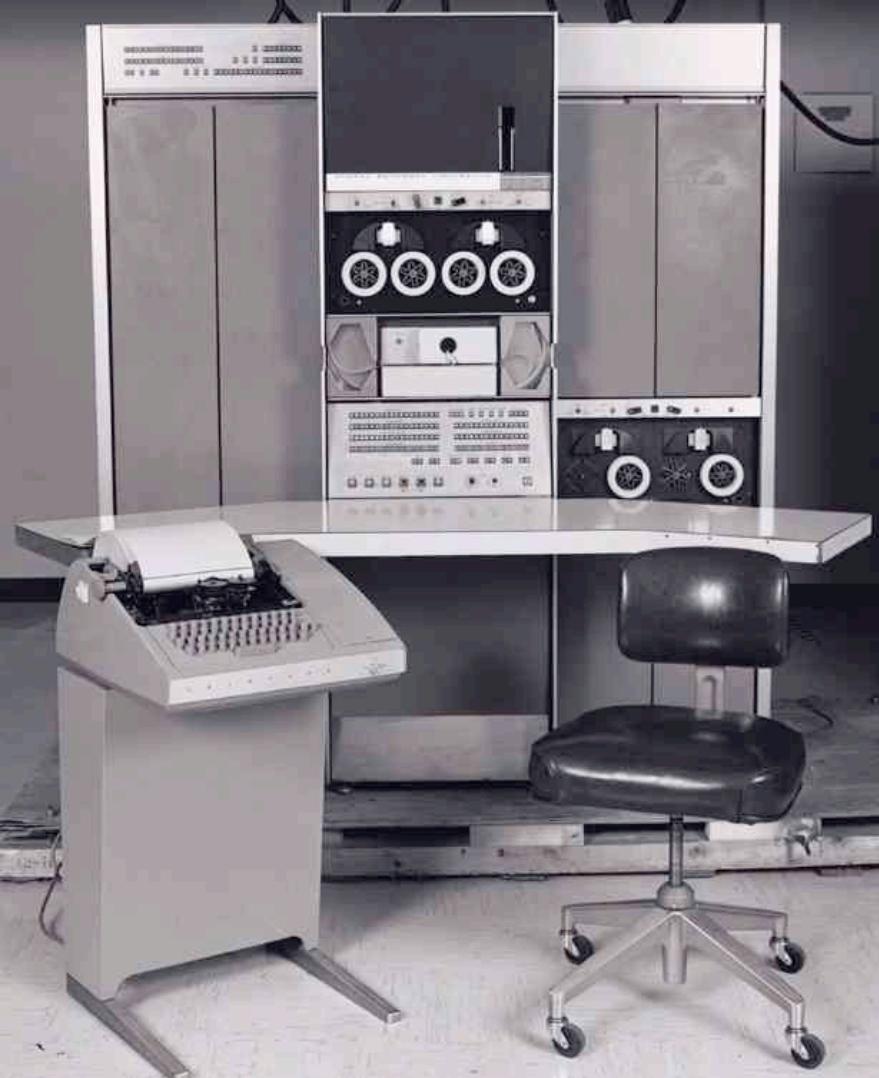
Since 1980's

- computers increasingly easy to program
- programs increasingly difficult to optimize



UMEÅ UNIVERSITY

“Good old days”



One country, one language



Cheong Suk-Wai, A borderless world

~~One country, one language~~



Cheong Suk-Wai, A borderless world

Language mismatch

Language mismatch



MUL

ADD

MOV

MOVAPD

VFMADDPD

$$K_k := P_k^b H^T (H P_k^b H^T + R)^{-1}; \quad x_k^a := x_k^b + K_k(z_k - Hx_k^b); \quad P_k^a := (I - K_k H) P_k^b$$

$$\begin{aligned}\tau_{ij}^{ab} &= t_{ij}^{ab} + \frac{1}{2} P_b^a P_j^i t_i^a t_j^b, \\ \tilde{F}_e^m &= f_e^m + \sum_{fn} v_{ef}^{mn} t_n^f,\end{aligned}$$

$$\begin{aligned}\Lambda &:= S(S^T AWAS)^{-1}S^T; \quad \Theta := \Lambda AW; \quad M_k := X_k A - I \\ X_{k+1} &:= X_k - M_k \Theta - (M_k \Theta)^T + \Theta^T (A X_k A - A) \Theta\end{aligned}$$

$$\begin{aligned}\tilde{F}_e^a &= (1 - \delta_{ae}) f_e^a - \sum_m \tilde{F}_e^m t_m^a - \frac{1}{2} \sum_{mnf} v_{ef}^{mn} t_{mn}^{af} + \sum_{fn} v_{ef}^{an} t_n^f, \\ \tilde{F}_i^m &= (1 - \delta_{mi}) f_i^m + \sum_e \tilde{F}_e^m t_i^e + \frac{1}{2} \sum_{nef} v_{ef}^{mn} t_{in}^{ef} + \sum_{fn} v_{if}^{mn} t_n^f,\end{aligned}$$

$$\left\{ \begin{array}{l} C_\dagger := PCP^T + Q \\ K := C_\dagger H^T (HC_\dagger H^T)^{-1} \end{array} \right.$$



$$K_k := P_k^b H^T (H P_k^b H^T + R)^{-1}; \quad x_k^a := x_k^b + K_k(z_k - Hx_k^b); \quad P_k^a := (I - K_k H) P_k^b$$

$$\tau_{ij}^{ab} = t_{ij}^{ab} + \frac{1}{2} P_b^a P_j^i t_i^a t_j^b,$$

$$\tilde{F}_e^m = f_e^m + \sum_{fn} v_{ef}^{mn} t_n^f,$$

$$\Lambda := S(S^T AWAS)^{-1}S^T; \quad \Theta := \Lambda AW; \quad M_k := X_k A - I \\ X_{k+1} := X_k - M_k \Theta - (M_k \Theta)^T + \Theta^T (A X_k A - A) \Theta$$

$$\tilde{F}_e^a = (1 - \delta_{ae}) f_e^a - \sum_m \tilde{F}_e^m t_m^a - \frac{1}{2} \sum_{mnf} v_{ef}^{mn} t_{mn}^{af} + \sum_{fn} v_{ef}^{an} t_n^f,$$

$$\tilde{F}_i^m = (1 - \delta_{mi}) f_i^m + \sum_e \tilde{F}_e^m t_i^e + \frac{1}{2} \sum_{nef} v_{ef}^{mn} t_{in}^{ef} + \sum_{fn} v_{if}^{mn} t_n^f,$$

$$\begin{cases} C_\dagger := PCP^T + Q \\ K := C_\dagger H^T (HC_\dagger H^T)^{-1} \end{cases}$$



MUL	ADD	MOV
MOVAPD		
VFMADDPD		

$$K_k := P_k^b H^T (H P_k^b H^T + R)^{-1}; \quad x_k^a := x_k^b + K_k(z_k - Hx_k^b); \quad P_k^a := (I - K_k H) P_k^b$$

$$\begin{cases} C_{\dagger} := PCP^T + Q \\ K := C_{\dagger} H^T (H C_{\dagger} H^T)^{-1} \end{cases}$$

$$\Lambda := S(S^T A W A S)^{-1} S^T; \quad \Theta := \Lambda A W; \quad M_k := X_k A - I \\ X_{k+1} := X_k - M_k \Theta - (M_k \Theta)^T + \Theta^T (A X_k A - A) \Theta$$

$$\boxed{y := \alpha x + y} \quad \boxed{LU = A} \quad \cdots \quad \boxed{C := \alpha AB + \beta C} \\ \boxed{X := A^{-1}B} \quad \boxed{C := AB^T + BA^T + C} \quad \boxed{X := L^{-1}ML^{-T}} \quad \boxed{QR = A}$$



MUL	ADD	MOV
MOVAPD		
VFMADDPD		

$$K_k := P_k^b H^T (H P_k^b H^T + R)^{-1}; \quad x_k^a := x_k^b + K_k(z_k - Hx_k^b); \quad P_k^a := (I - K_k H) P_k^b$$

$$\begin{cases} C_{\dagger} := PCP^T + Q \\ K := C_{\dagger} H^T (H C_{\dagger} H^T)^{-1} \end{cases}$$

$$\Lambda := S(S^T A W A S)^{-1} S^T; \quad \Theta := \Lambda A W; \quad M_k := X_k A - I \\ X_{k+1} := X_k - M_k \Theta - (M_k \Theta)^T + \Theta^T (A X_k A - A) \Theta$$



$$\boxed{y := \alpha x + y} \quad \boxed{LU = A} \quad \cdots \quad \boxed{C := \alpha AB + \beta C} \\ \boxed{X := A^{-1}B} \quad \boxed{C := AB^T + BA^T + C} \quad \boxed{X := L^{-1}ML^{-T}} \quad \boxed{QR = A}$$

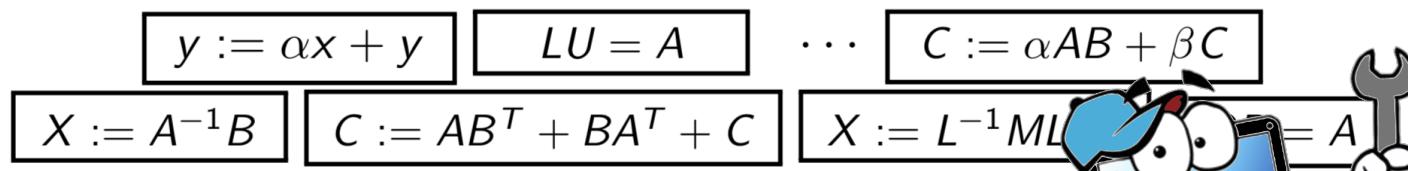


MUL	ADD	MOV
MOVAPD		
VFMADDPD		

$$K_k := P_k^b H^T (H P_k^b H^T + R)^{-1}; \quad x_k^a := x_k^b + K_k(z_k - Hx_k^b); \quad P_k^a := (I - K_k H) P_k^b$$

$$\begin{cases} C_{\dagger} := PCP^T + Q \\ K := C_{\dagger} H^T (H C_{\dagger} H^T)^{-1} \end{cases}$$

$$\Lambda := S(S^T A W A S)^{-1} S^T; \quad \Theta := \Lambda A W; \quad M_k := X_k A - I \\ X_{k+1} := X_k - M_k \Theta - (M_k \Theta)^T + \Theta^T (A X_k A - A) \Theta$$



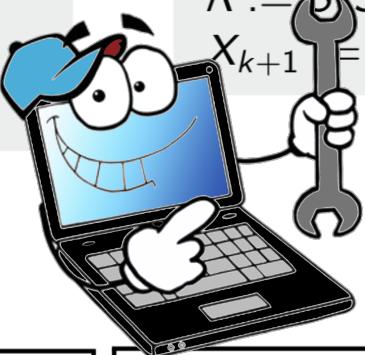
MUL ADD MOV
MOVAPD
VEMADDPD

$$K_k := P_k^b H^T (H P_k^b H^T + R)^{-1}; \quad x_k^a := x_k^b + K_k(z_k - Hx_k^b); \quad P_k^a := (I - K_k H) P_k^b$$

$$\begin{cases} C_{\dagger} := PCP^T + Q \\ K := C_{\dagger} H^T (H C_{\dagger} H^T)^{-1} \end{cases}$$

$$\Lambda := S(S^T A W A S)^{-1} S^T; \quad \Theta := \Lambda A W; \quad M_k := X_k A - I$$

$$X_{k+1} = X_k - M_k \Theta - (M_k \Theta)^T + \Theta^T (A X_k A - A) \Theta$$



$y := \alpha x + y$

$LU = A$

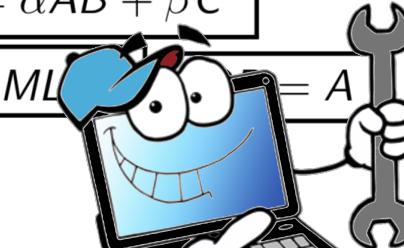
\dots

$C := \alpha AB + \beta C$

$X := A^{-1}B$

$C := AB^T + BA^T + C$

$X := L^{-1}ML = A$



MUL ADD MOV
MOVAPD
VEMADDPD

PotC

EAM Potential

```
parameter cutoff = file(1);
parameter grid_size_rho = file(2);
parameter grid_size = file(3);
parameter rho(i : atom_type; j : atom_type; r :
    ↳ distance) =
    spline_grid(rho, 3, 0, grid_size, 3);
parameter F(i : atom_type; r : real) =
    spline_grid(F, 3, 0, grid_size_rho, 1);
parameter phi(i : atom_type; j : atom_type; r :
    ↳ distance) =
    spline_grid(phi, 3, 0, grid_size, 3);

peratom rho_sum(i : atom) = sum(j : neighbors(i,
    ↳ cutoff)) rho(i, j, r(i, j));

energy sum(i : all_atoms) F(i, rho_sum(i));
energy sum(i : all_atoms) sum(j : neighbors_half(i,
    ↳ cutoff)) phi(i, j, r(i, j)) / r(i, j);
```

PotC

```
bvec t_0=bvec::full();
for(int t_1=iafrom; t_1<iato; t_1+=fvec::VL){
    ivec i_i_2=ivec::set_consecutive() + ivec::set1(t_1);
    bvec t_2=bvec::kand(bvec::full(), ivec::cmplt(i_i_2, ivec::set1(iato)));
    fvec::mask_scatter_double_zero(peratom_rho_sum, t_2, i_i_2);
    fvec::mask_scatter_double_zero(peratom_adjoint_rho_sum, t_2, i_i_2);
}
#endif _OPENMP
#pragma omp barrier
#endif
fvec i_param_10=(ONETYPE?fvec::set1(this->param_cutoff):fvec::mask_gather_double(t_0, ivec::setzero(), &this->param_cutoff));
for(int t_3=iifrom; t_3<iito; t_3+=fvec::VL){
    ivec i_i_3=ivec::set_consecutive() + ivec::set1(t_3);
    bvec t_4=bvec::kand(bvec::full(), ivec::cmplt(i_i_3, ivec::set1(iito)));
    fvec i_px_4=fvec::mask_gather<4>(fvec::undefined(), t_4, ivec::mul_fwidth(i_i_3), &x[0].x);
    fvec i_py_4=fvec::mask_gather<4>(fvec::undefined(), t_4, ivec::mul_fwidth(i_i_3), &x[0].y);
    fvec i_pz_4=fvec::mask_gather<4>(fvec::undefined(), t_4, ivec::mul_fwidth(i_i_3), &x[0].z);
    ivec i_ty_4=ivec::mask_gather(ivec::undefined(), t_4, ivec::mul_fwidth(i_i_3), &x[0].w, 4);
    fvec i_a_5=fvec::setzero();
    ivec i_i_6=ivec::setzero();
    ivec t_5=ivec::mask_gather(ivec::undefined(), t_4, i_i_3, numneigh, 4);
    for(;;){
        bvec t_6=bvec::kand(t_4, ivec::cmplt(i_i_6, t_5));
        if(bvec::test_all_unset(t_6)) break;
        ivec i_a_7=ivec::mask_gather(ivec::undefined(), t_6, ivec::mask_gather(ivec::undefined(), t_6, i_i_3, cnumneigh, 4)+(i_i_6),
        firstneigh, 4);
        fvec i_px_8=fvec::mask_gather<4>(fvec::undefined(), t_6, ivec::mul_fwidth(i_a_7), &x[0].x);
        fvec i_py_8=fvec::mask_gather<4>(fvec::undefined(), t_6, ivec::mul_fwidth(i_a_7), &x[0].y);
        fvec i_pz_8=fvec::mask_gather<4>(fvec::undefined(), t_6, ivec::mul_fwidth(i_a_7), &x[0].z);
        ivec i_ty_8=ivec::mask_gather(ivec::undefined(), t_6, ivec::mul_fwidth(i_a_7), &x[0].w, 4);
        fvec i_dx_9=((i_px_4)-(i_px_8));
        fvec i_dy_9=((i_py_4)-(i_py_8));
        fvec i_dz_9=((i_pz_4)-(i_pz_8));
        fvec i_rsq_9((((i_dx_9)*(i_dx_9))+((i_dy_9)*(i_dy_9))))+(((i_dz_9)*(i_dz_9)));
        bvec t_7=bvec::kand(fvec::cmplnlt(i_rsq_9, (((i_param_10)*(i_param_10)))), t_6);
        if(bvec::test_any_set(t_7)){
            i_i_6.ives::mask_add(i_i_6.t_7, i_i_6.ives::set1, 1);
        }
    }
}
```

1177
lines of code

Linnea

Kalman Filter

$$K_k := P_k^b H^T (H P_k^b H^T + R)^{-1};$$

$$x_k^a := x_k^b + K_k(z_k - H x_k^b);$$

$$P_k^a := (I - K_k H) P_k^b$$

$$K_k \in \mathbb{R}^{n \times m}; P_k^b \in \mathbb{R}^{n \times n}, \text{SPD};$$

$$H \in \mathbb{R}^{m \times n}, \text{SPD}; R \in \mathbb{R}^{m \times m}, \text{SPSD};$$

$$x_k^b \in \mathbb{R}^{n \times 1}; z_k \in \mathbb{R}^{m \times 1}; n = 400; m = 500$$

Linnea

```
function algorithmo(ml0::Array{Float64,2}, ml1::Array{Float64,2}, ml2::Array{Float64,2}, ml3::Array{Float64,1}, ml4::Array{Float64,1})
    start::Float64 = 0.0
    finish::Float64 = 0.0
    Benchmarker.cachescrub()
    start = time_ns()

    # cost 5.34e+08
    # P_b: ml0, full, H: ml1, full, R: ml2, full, x_b: ml3, full, zk: ml4, full
    ml5 = Array{Float64}(undef, 400, 400)
    # tmp63 = (H P_b)
    symm!('R', 'L', 1.0, ml0, ml1, 0.0, ml5)

    # P_b: ml0, full, H: ml1, full, R: ml2, full, x_b: ml3, full, zk: ml4, full, tmp63: ml5, full
    ml6 = Array{Float64}(undef, 400, 400)
    # tmp62 = tmp63^T
    transpose!(ml6, ml5)

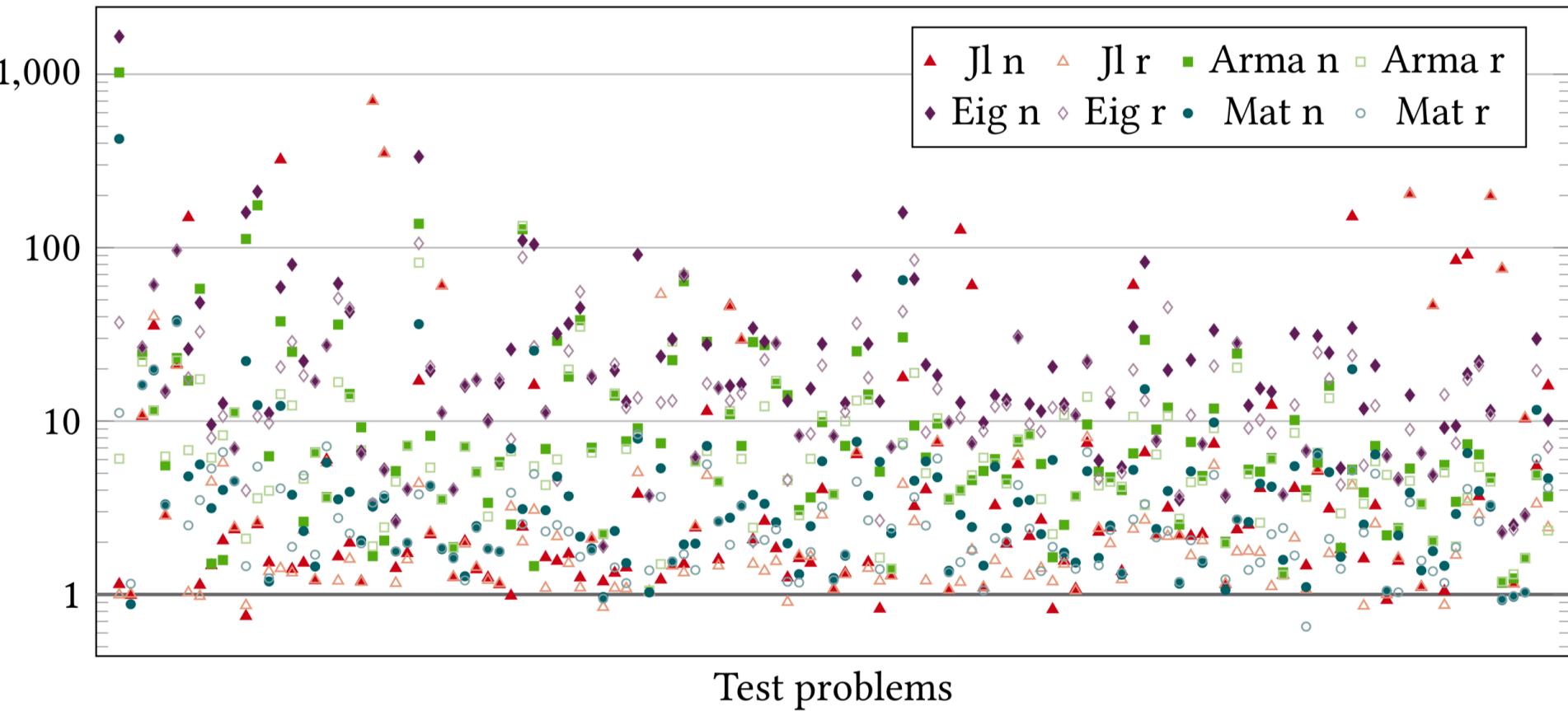
    # P_b: ml0, full, H: ml1, full, R: ml2, full, x_b: ml3, full, zk: ml4, full, tmp62: ml6, full
    # tmp19 = (R + (H tmp62))
    gemm!('N', 'N', 1.0, ml1, ml6, 1.0, ml2)

    # P_b: ml0, full, H: ml1, full, x_b: ml3, full, zk: ml4, full, tmp62: ml6, full, tmp19: ml2, full
    # (L64 L64^T) = tmp19
    LinearAlgebra.LAPACK.potrf!("L", ml2)

    # P_b: ml0, full, H: ml1, full, x_b: ml3, full, zk: ml4, full, tmp62: ml6, full, L64: ml2, lower_triangular
    ml7 = Array{Float64}(undef, 400, 400)
    blascopy!(400*400, ml6, 1, ml7, 1)
    # tmp70 = (tmp62 L64^-T)
    trsm!('R', 'L', 'T', 'N', 1.0, ml2, ml6)
```

Linnea

Speedup



Thank you

Speedup

