

Tensor Computations: Efficiency Or Productivity?

Paolo Bientinesi – Umeå Universitet & RWTH Aachen University

Rasmus Bro – University of Copenhagen

Edoardo Di Napoli – Jülich Supercomputing Centre

Lars Karlsson – Umeå Universitet

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**High Performance and
Automatic Computing**

Part I
The HPC perspective

Disclaimer: Talk about awareness, not results

Typical HPC “workflow” – not limited to tensor computations

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- ▶ Fixed problem size?
- ▶ Target architecture? (parallel paradigm)

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⇒ **Caveat:** Gains in the building blocks... often lost at the higher levels

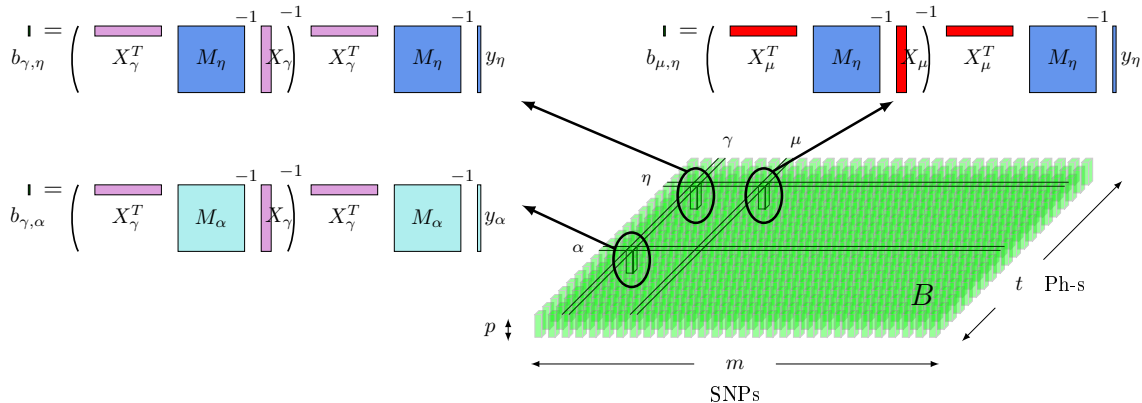
- ▶ What is it? Data correlation analysis. 2D grid of generalized least squares problems (GLS)

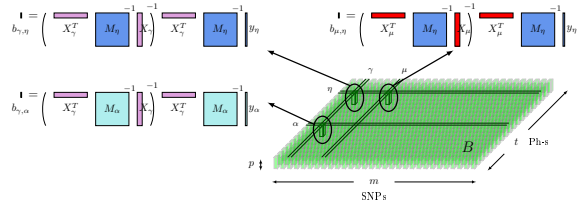
Examples (1/2)

Genome-Wide Association Studies (GWAS)

► How is it related to tensors?

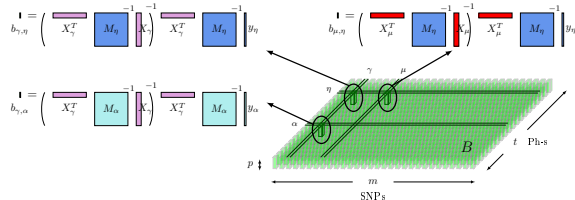
1D×1D cartesian product of GLSs, 2D output = 4D data





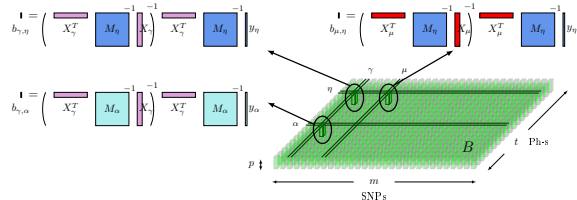
- ▶ Algorithmic improvement: lower computational complexity
- ▶ HPC optimizations: asynch I/O, overlap, BLAS-3, parallelism, ...

*Computing Petaflops over Terabytes of Data:
The Case of Genome-Wide Association Studies.*
ACM TOMS, 2014



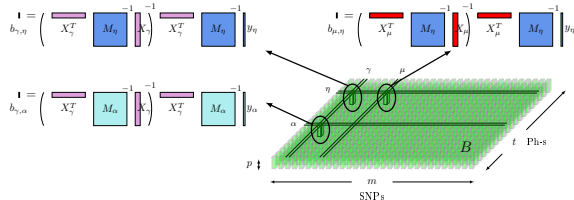
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- ▶ 100x – 1000x speedups! 😊 Library available: OmicABEL 🐱

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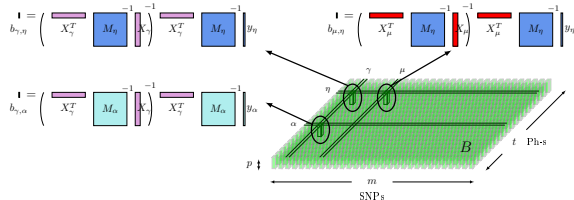
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 - ▶ Interface: C vs. R
 - ▶ Data management: data formats, overwriting, multiple files
 - ▶ Data manipulation: imputation, filtering, selection
 - ▶ Workflow not as fixed as first understood: M vs no-M, ...
 - ▶ *“The pre-processing is slower than the analysis”*

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⇒ Performance is important, but not as much as we like to think

▶ **Tensor Transpositions**

$$\mathcal{B}_{i_1 i_2 \dots i_N} \leftarrow \alpha \cdot \mathcal{A}_{\pi(i_1 i_2 \dots i_N)} + \beta \cdot \mathcal{B}_{i_1 i_2 \dots i_N}$$

▶ **Summations** — linear summation over tensor transpositions

$$\mathcal{B}_{i_0 i_1 i_2} \leftarrow 2\mathcal{A}_{i_0 i_1 i_2} - \mathcal{A}_{i_2 i_1 i_0} - \mathcal{A}_{i_0 i_2 i_1}$$

$$\mathcal{B}_{i_0 i_1 i_2} \leftarrow 4\mathcal{A}_{i_0 i_1 i_2} - 2\mathcal{A}_{i_1 i_0 i_2} - 2\mathcal{A}_{i_2 i_1 i_0} + \mathcal{A}_{i_1 i_2 i_0} - 2\mathcal{A}_{i_0 i_2 i_1} + \mathcal{A}_{i_2 i_0 i_1}$$

$$\mathcal{B}_{i_0 i_1 i_2 i_3} \leftarrow 2\mathcal{A}_{i_0 i_1 i_2 i_3} - \mathcal{A}_{i_2 i_1 i_0 i_3} - \mathcal{A}_{i_0 i_2 i_1 i_3} - \mathcal{A}_{i_0 i_1 i_3 i_2}$$

▶ **Tensor Contractions**

$$\mathcal{C}_{\pi_C(I_m \cup I_n)} \leftarrow \alpha \cdot \mathcal{A}_{\pi_A(I_m \cup I_k)} \times \mathcal{B}_{\pi_B(I_n \cup I_k)} + \beta \cdot \mathcal{C}_{\pi_C(I_m \cup I_n)}$$

▶ Tensor Transpositions

TTC: A high-performance Compiler for Tensor Transpositions. ACM TOMS, 2017

Compiler: <https://github.com/HPAC/TTC> **Library:** <https://github.com/HPAC/hptt>



▶ Summations — linear summation over tensor transpositions

Spin Summations: A High-Performance Perspective. ACM TOMS, 2019

Generator: <https://github.com/springer13/spin-summations>



▶ Tensor Contractions

Design of a high-performance GEMM-like Tensor-Tensor Multiplication. ACM TOMS, 2018

Compiler: <https://github.com/HPAC/tccg> **Library:** <https://github.com/springer13/tcl>



But...

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- ▶ “Wrong” level of abstraction for domain scientists
- ▶ Kernels: good for developers – too low level for most end users
- ▶ Mismatch → mapping problem

2D case: "Right" level of abstraction

Generalized Least Squares $b := (X^T M^{-1} X)^{-1} X^T M^{-1} y$ $n > m; M \in \mathbb{R}^{n \times n}, \text{SPD}; X \in \mathbb{R}^{n \times m}; y \in \mathbb{R}^{n \times 1}$

Signal Processing $x := (A^{-T} B^T B A^{-1} + R^T L R)^{-1} A^{-T} B^T B A^{-1} y$

Kalman Filter $K_k := P_k^b H^T (H P_k^b H^T + R)^{-1}; x_k^a := x_k^b + K_k (z_k - H x_k^b); P_k^a := (I - K_k H) P_k^b$

Ensemble Kalman Filter $X^a := X^b + (B^{-1} + H^T R^{-1} H)^{-1} (Y - H X^b)$

Image Restoration $x_k := (H^T H + \lambda \sigma^2 I_n)^{-1} (H^T y + \lambda \sigma^2 (v_{k-1} - u_{k-1}))$

Rand. Matrix Inversion $X_{k+1} := S(S^T A S)^{-1} S^T + (I_n - S(S^T A S)^{-1} S^T A) X_k (I_n - A S(S^T A S)^{-1} S^T)$

Stochastic Newton $B_k := \frac{k}{k-1} B_{k-1} (I_n - A^T W_k ((k-1)I_l + W_k^T A B_{k-1} A^T W_k)^{-1} W_k^T A B_{k-1})$

Optimization $x_f := W A^T (A W A^T)^{-1} (b - A x); x_o := W (A^T (A W A^T)^{-1} A x - c)$

Tikhonov Regularization $x := (A^T A + \Gamma^T \Gamma)^{-1} A^T b$ $A \in \mathbb{R}^{n \times m}; \Gamma \in \mathbb{R}^{m \times m}; b \in \mathbb{R}^{n \times 1}$

Gen. Tikhonov Reg. $x := (A^T P A + Q)^{-1} (A^T P b + Q x_0)$ $P \in \mathbb{R}^{n \times n}, \text{SSPD}; Q \in \mathbb{R}^{m \times m}, \text{SSPD}; x_0 \in \mathbb{R}^{m \times 1}$

LMMSE estimator $K_{t+1} := C_t A^T (A C_t A^T + C_z)^{-1}; x_{t+1} := x_t + K_{t+1} (y - A x_t); C_{t+1} := (I - K_{t+1} A) C_t$

$$x := A(B^T B + A^T R^T \Lambda R A)^{-1} B^T B A^{-1} y$$

$$\begin{cases} C_{\dagger} := P C P^T + Q \\ K := C_{\dagger} H^T (H C_{\dagger} H^T)^{-1} \end{cases}$$

$$E := Q^{-1} U (I + U^T Q^{-1} U)^{-1} U^T \quad \dots$$



- MUL
- ADD
- MOV
- MOVAPD
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- ...

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$$y := \alpha x + y \quad LU = A \quad \dots \quad C := \alpha AB + \beta C$$

$$X := A^{-1} B \quad C := AB^T + BA^T + C \quad X := L^{-1} M L^{-T} \quad QR = A$$

BLAS



...



LAPACK

...



MUL ADD MOV

MOVAPD

VFMADDPD ...

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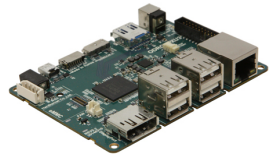
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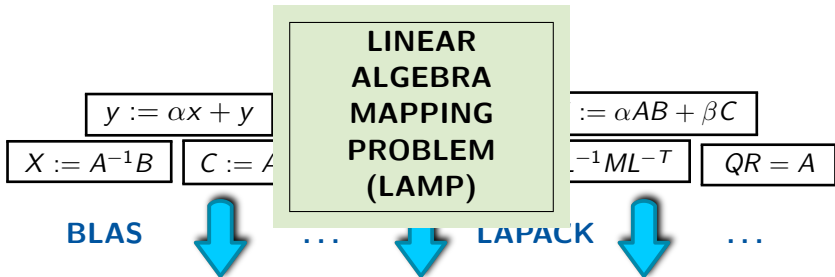


MUL	ADD	MOV
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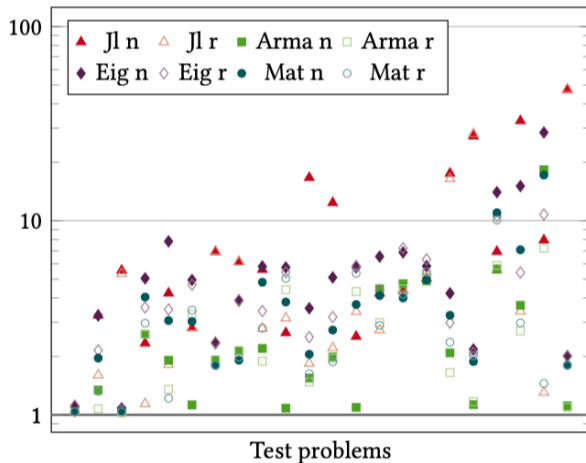


- MUL ADD MOV
- MOVAPD
- VFMADDPD ...

LAMP: A problem often ignored

Linnea: A compiler for linear algebra – Henrik Barthels, Christos Psarras

Linnea's speedups



Jl: Julia, **Arma:** Armadillo, **Eig:** Eigen, **Mat:** Matlab.

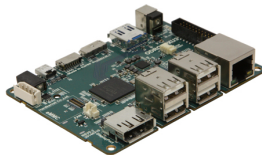
n/r: naive/recommended implementation

Tensor App #1

Tensor App #2

...

Tensor App #N



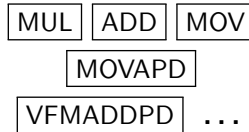
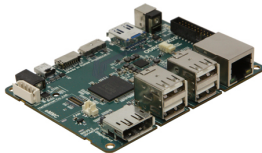
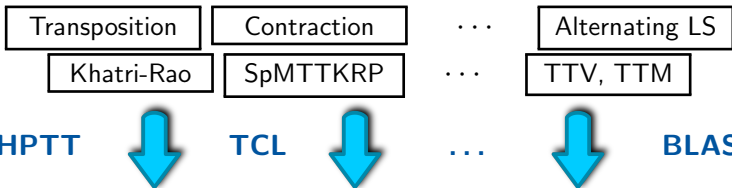
MUL ADD MOV
MOVAPD
VFMADDPD ...

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Tensor App #2

...

Tensor App #N



nD case: Exemplary applications

Coupled-Cluster methods

$$\tilde{\tau}_{ij}^{ab} = t_{ij}^{ab} + \frac{1}{2} P_b^a P_j^i t_i^a t_j^b,$$

$$\tilde{F}_e^m = f_e^m + \sum_{fn} v_{ef}^{mn} t_n^f,$$

$$\tilde{F}_e^a = (1 - \delta_{ae}) f_e^a - \sum_m \tilde{F}_e^m t_m^a - \frac{1}{2} \sum_{mnf} v_{ef}^{mn} t_{mn}^{af} + \sum_{fn} v_{ef}^{an} t_n^f,$$

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$$\tilde{W}_{ei}^{mn} = v_{ei}^{mn} + \sum_f v_{ef}^{mn} t_i^f,$$

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$$\tilde{W}_{ie}^{am} = v_{ie}^{am} - \sum_n \tilde{W}_{ei}^{mn} t_n^a + \sum_f v_{ef}^{ma} t_i^f + \frac{1}{2} \sum_{nf} v_{ef}^{mn} t_{in}^{af},$$

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$$z_i^a = f_i^a - \sum_m \tilde{F}_i^m t_m^a + \sum_e f_e^a t_i^e + \sum_{em} v_{ei}^{ma} t_m^e + \sum_{em} v_{im}^{ae} \tilde{F}_e^m + \frac{1}{2} \sum_{efm}$$

$$z_{ij}^{ab} = v_{ij}^{ab} + P_j^i \sum_e v_{ie}^{ab} t_j^e + P_b^a P_j^i \sum_{me} \tilde{W}_{ie}^{am} t_{mj}^{eb} - P_b^a \sum_m \tilde{W}_{ij}^{am} t_m^b + P$$

credits to D. Matthews, E. Solomonik, J. Stanton, and J. Gauss

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$$z_{ij}^{ab} = v_{ij}^{ab} + P_j^i \sum_e v_{ie}^{ab} t_j^e + P_b^a P_j^i \sum_{me} \tilde{W}_{ie}^{am} t_{mj}^{eb} - P_b^a \sum_m \tilde{W}_{ij}^{am} t_m^b + P$$

Finite Element 3D diffusion operator

```
TE.BeginMultiKernelLaunch();
TE("T2_e_i1_i2_k3 = B_k3_i3 X_e_i1_i2_i3", T2, B, X);
TE("T1_e_i1_k2_k3 = B_k2_i2 T2_e_i1_i2_k3", T1, B, T2);
TE("U1_e_k1_k2_k3 = G_k1_i1 T1_e_i1_k2_k3", U1, G, T1);
TE("T1_e_i1_k2_k3 = G_k2_i2 T2_e_i1_i2_k3", T1, G, T2);
TE("U2_e_k1_k2_k3 = B_k1_i1 T1_e_i1_k2_k3", U2, B, T1);
TE("T2_e_i1_i2_k3 = G_k3_i3 X_e_i1_i2_i3", T2, G, X);
TE("T1_e_i1_k2_k3 = B_k2_i2 T2_e_i1_i2_k3", T1, B, T2);
TE("U3_e_k1_k2_k3 = B_k1_i1 T1_e_i1_k2_k3", U3, B, T1);
TE("Z_m_e_k1_k2_k3 = U_n_e_k1_k2_k3 D_e_m_n_k1_k2_k3", Z, U,
TE("T1_e_i3_k1_k2 = B_k3_i3 Z1_e_k1_k2_k3", T1, B, Z1);
TE("T2_e_i2_i3_k1 = B_k2_i2 T1_e_i3_k1_k2", T2, B, T1);
TE("Y_e_i1_i2_i3 = G_k1_i1 T2_e_i2_i3_k1", Y, G, T2);
TE("T1_e_i3_k1_k2 = B_k3_i3 Z2_e_k1_k2_k3", T1, B, Z2);
TE("T2_e_i2_i3_k1 = G_k2_i2 T1_e_i3_k1_k2", T2, G, T1);
TE("Y_e_i1_i2_i3 += B_k1_i1 T2_e_i2_i3_k1", Y, B, T2);
TE("T1_e_i3_k1_k2 = G_k3_i3 Z3_e_k1_k2_k3", T1, G, Z3);
TE("T2_e_i2_i3_k1 = B_k2_i2 T1_e_i3_k1_k2", T2, B, T1);
TE("Y_e_i1_i2_i3 += B_k1_i1 T2_e_i2_i3_k1", Y, B, T2);
TE.EndMultiKernelLaunch();
```

credits to D. Matthews, E. Solomonik, J. Stanton, and J. Gauss

credits to A. Fisher – <https://github.com/LLNL/acrotensor>

Awareness

- ▶ **Performance:**
Speedups in building blocks do not always translate to speedups in applications

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Speedups in building blocks do not always translate to speedups in applications

 - ▶ **Research Problem:** Mapping onto building blocks
 - ▶ Solved by hand → loss of productivity (possibly loss of efficiency too)
 - ▶ Solved automatically → loss of efficiency
- Beware:** It's challenging even for “simple” matrix computations!

Part II

The computational scientists' perspective

“The fastest FLOPS are those that are not executed.”

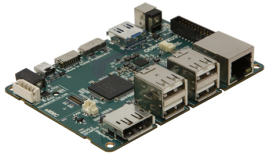
– Lars

Chromatography-MS

PARAFAC Tucker PARAFAC2

Transposition Contraction ... Alternating LS
Khatri-Rao SpMTTKRP ... TTV, TTM

HPTT TCL ... BLAS

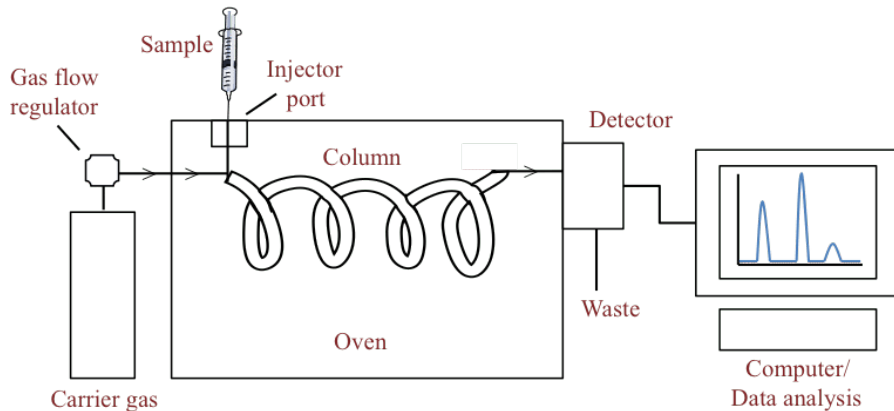


MUL ADD MOV
MOVAPD
VFMADDPD ...

Example application: Untargeted chemical profiling

Chromatography with mass spectrometry detection

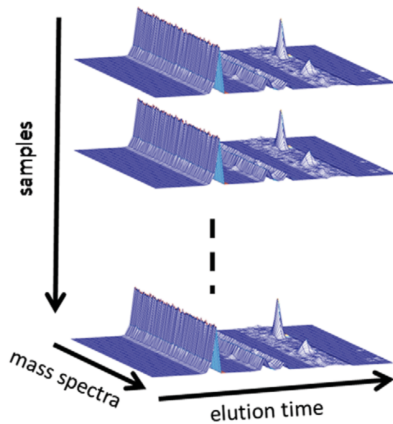
- ▶ Problem: Identify components in a sample



Example application: Untargeted chemical profiling

Chromatography with mass spectrometry detection

- ▶ 3-way data: Mass-spectrum \times elution time \times sample

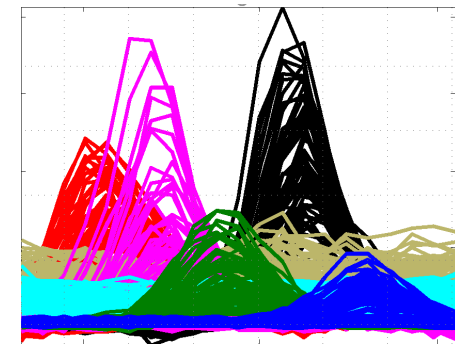


Rasmus Bro

Example application: Untargeted chemical profiling

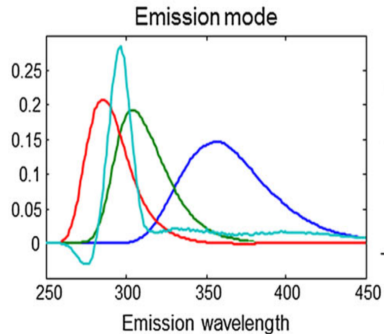
Chromatography with mass spectrometry detection

- ▶ 3-way tensor \rightarrow Individual components



Rasmus Bro

\rightarrow



Workflow

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 - ▶ 😊: Determine which of the components represent chemical information
 - ▶ 😞: Start over; add/change constraints, change model

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Speedups in building blocks do not always translate to speedups in applications

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- ▶ Solved by hand → loss of productivity (possibly loss of efficiency too)

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Thank you

Questions?

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