

Linnea: Automatic Generation of Efficient Linear Algebra Programs

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Introduction

- How to compute the following expressions?

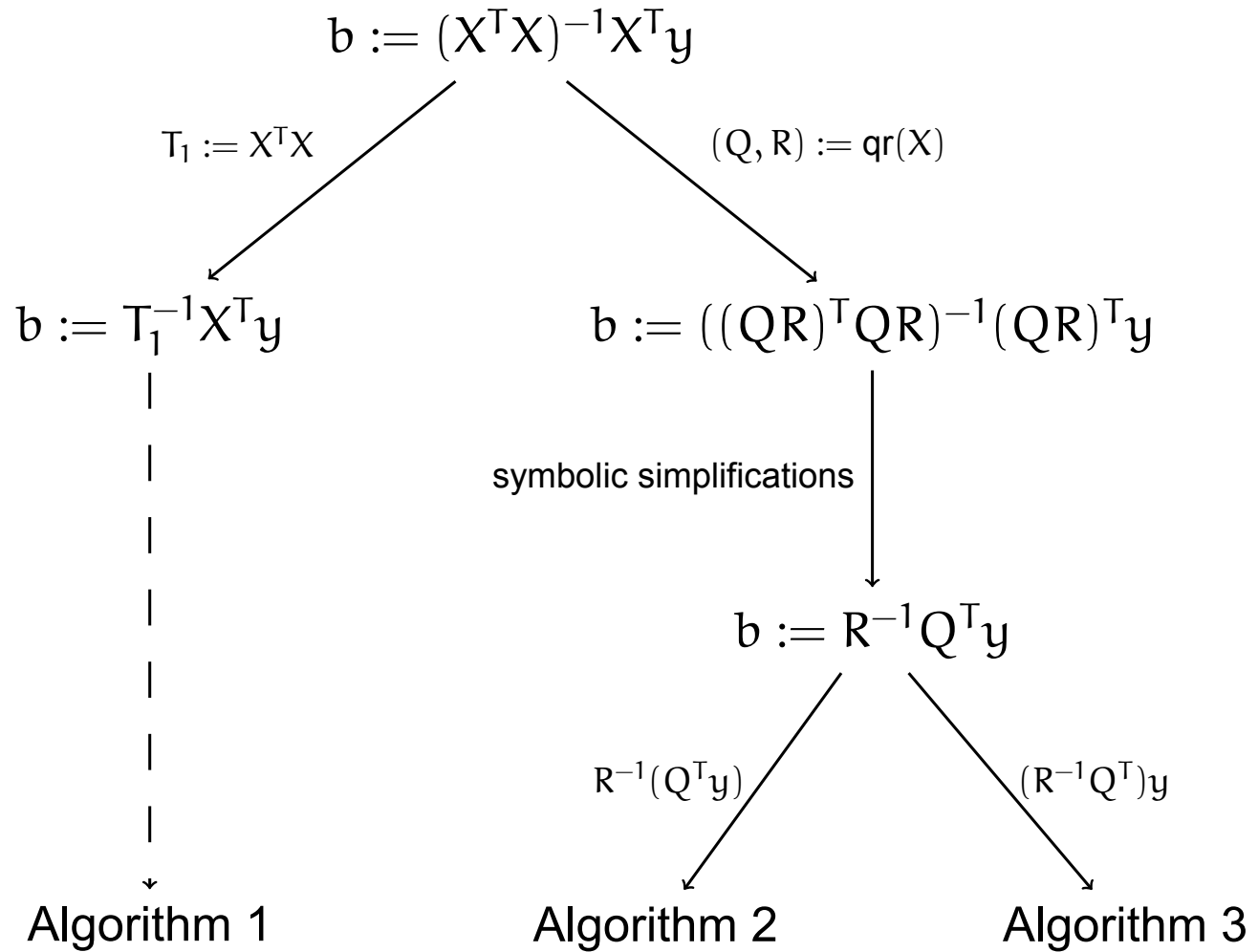
$$\mathbf{b} := (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

$$\mathbf{b} := (\mathbf{X}^T \mathbf{M}^{-1} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{M}^{-1} \mathbf{y}$$

$$\mathbf{x} := \mathbf{W} (\mathbf{A}^T (\mathbf{A} \mathbf{W} \mathbf{A}^T)^{-1} \mathbf{b} - \mathbf{c})$$

$$\mathbf{x} := (\mathbf{A}^{-T} \mathbf{B}^T \mathbf{B} \mathbf{A}^{-1} + \mathbf{R}^T [\Lambda(\mathbf{R} \mathbf{z})] \mathbf{R})^{-1} \mathbf{A}^{-T} \mathbf{B}^T \mathbf{B} \mathbf{A}^{-1} \mathbf{y}$$

- High-level languages are easy to use, but performance is usually suboptimal.
- BLAS and LAPACK can be fast, but require a lot of expertise.
- Goal: Simplicity **and** performance.



Input

$n = 1500$

$m = 1000$

Matrix $M(n, n)$ <Input, SPD>

Matrix $X(n, m)$ <Input, FullRank>

ColumnVector $y(n)$ <Input>

ColumnVector $b(m)$ <Output>

$$b = \text{inv}(X' * \text{inv}(M) * X) * X' * \text{inv}(M) * y$$

Instruction Set

BLAS [DDC⁺90]

- $y \leftarrow Ax + y$
- $C \leftarrow AB + C$
- $B \leftarrow A^{-1}B$
- ...

LAPACK [AB⁺99]

- Matrix factorizations.
- Eigensolvers.
- Solvers for linear systems with specific properties.

Properties

Operation	Cost
$\boxed{\cancel{A^{-1}} \quad B}$	n^3
$\boxed{A^{-1}} \quad \boxed{B}$	$2.7n^3$

Inference of Properties

$$\begin{array}{ccc} \boxed{A} & \rightarrow & \boxed{A^T} \\ \boxed{A} \quad \boxed{B} & \rightarrow & \boxed{AB} \\ \text{expr} = \text{expr}^T & \rightarrow & \text{Symmetric}(\text{expr}) \end{array}$$

Simplifications

$$(AB)^T \rightarrow B^T A^T$$

$$A^T \rightarrow A$$

$$Q^T Q \rightarrow I$$

if Symmetric(A)

if Orthogonal(Q)

Rewriting Expressions

$$X := AB + AC \quad \rightarrow \quad X := A(B + C)$$

$$X := A^T A + A^T B + B^T A \quad \rightarrow \quad \begin{array}{l} Y := B + A/2 \\ X := A^T Y + Y^T A \end{array}$$

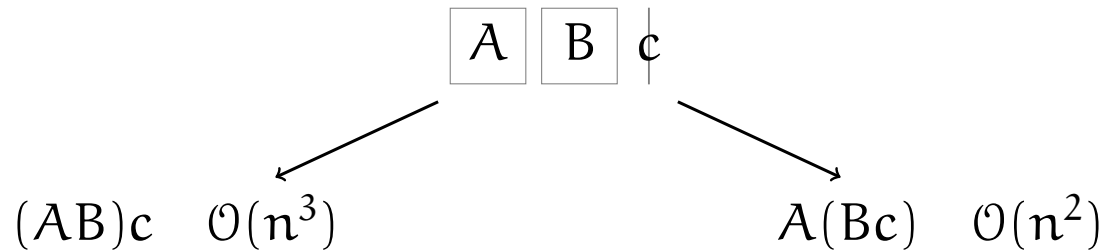
$$X := (\alpha I + Q^T W Q) \quad \rightarrow \quad \begin{array}{l} Y := \alpha I + W \\ X := Q^T Y Q \end{array}$$

Common Subexpression Elimination

$$\begin{array}{l} X := AB^{-T}C \\ Y := B^{-1}A^TC \end{array} \rightarrow \begin{array}{l} Z := AB^{-T} \\ X := ZC \\ Y := Z^TC \end{array}$$

$$AB^{-T} = (B^{-1}A^T)^T = Z$$

Generalized Matrix Chain Problem



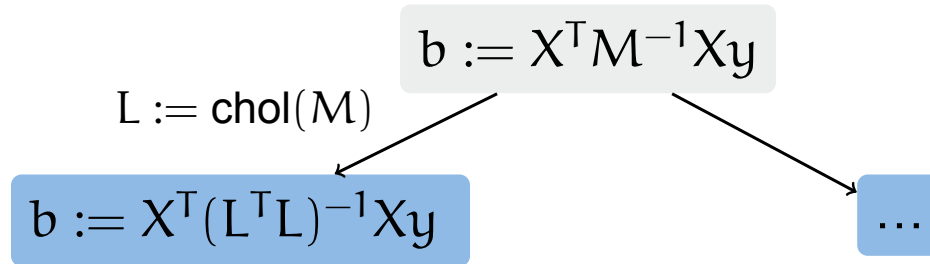
In practice:

$$X := AB^T C^{-T} D$$

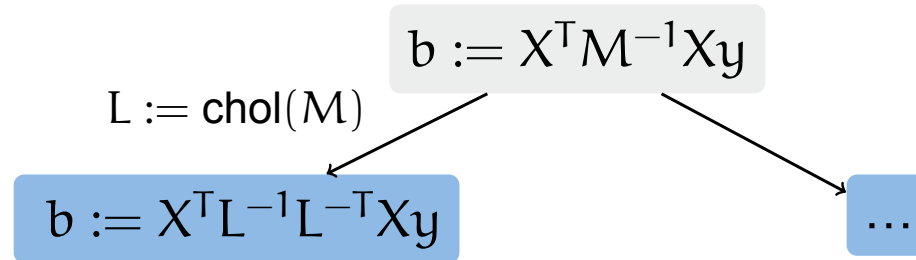
Derivation Graph

$$b := X^T M^{-1} X y$$

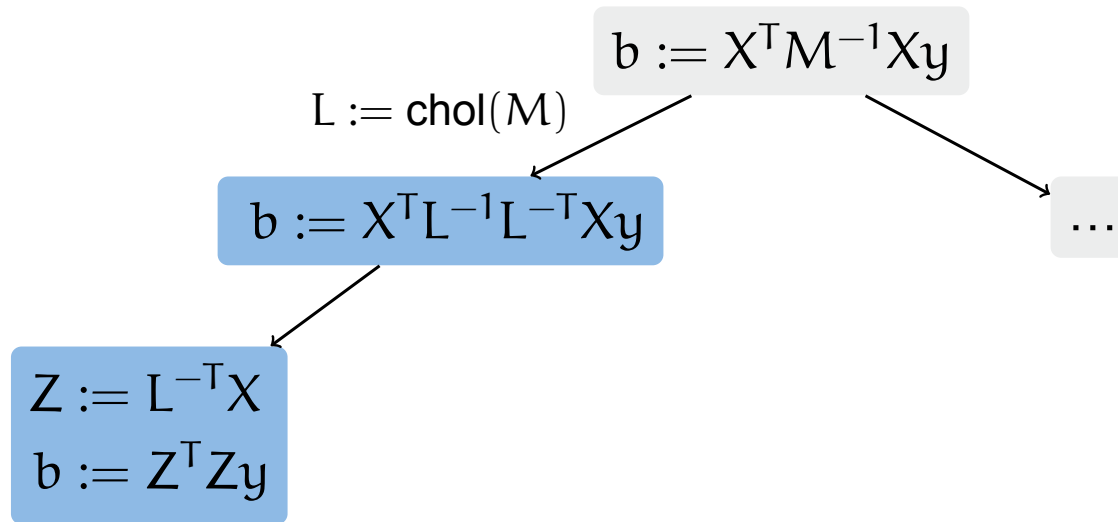
Derivation Graph



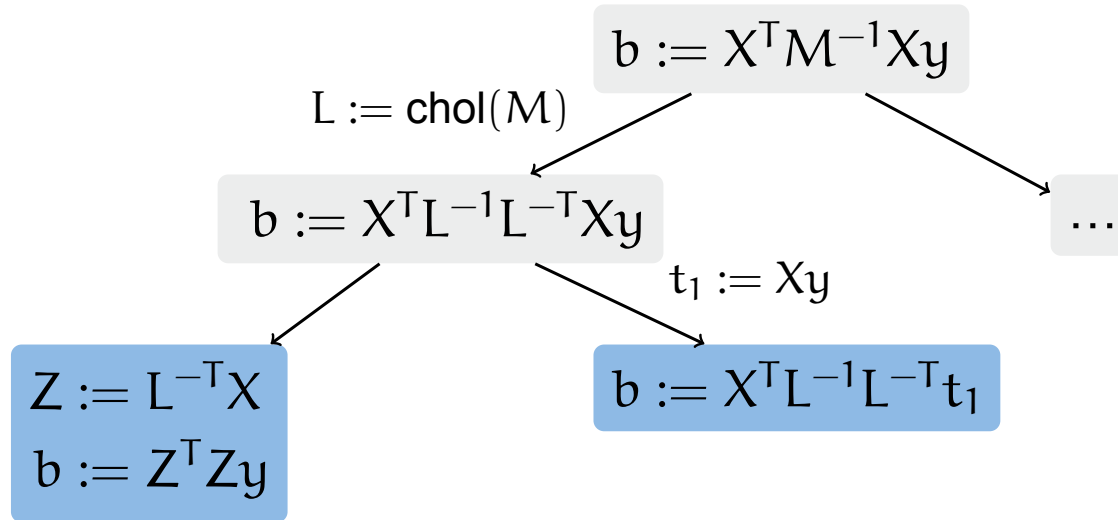
Derivation Graph



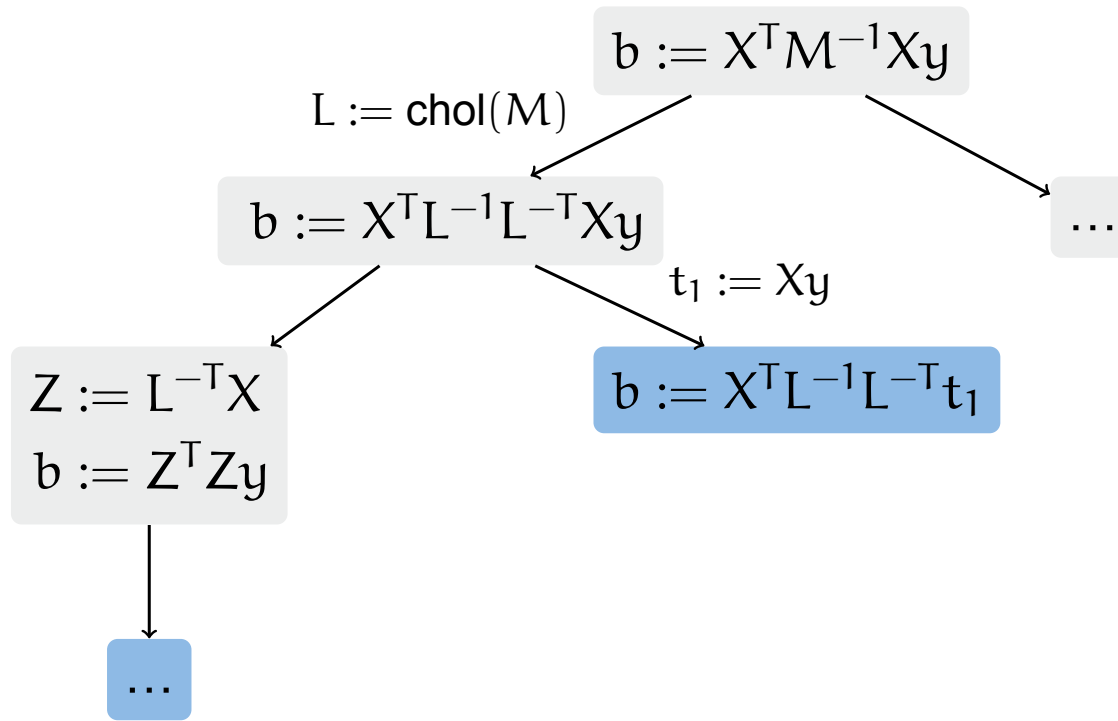
Derivation Graph



Derivation Graph

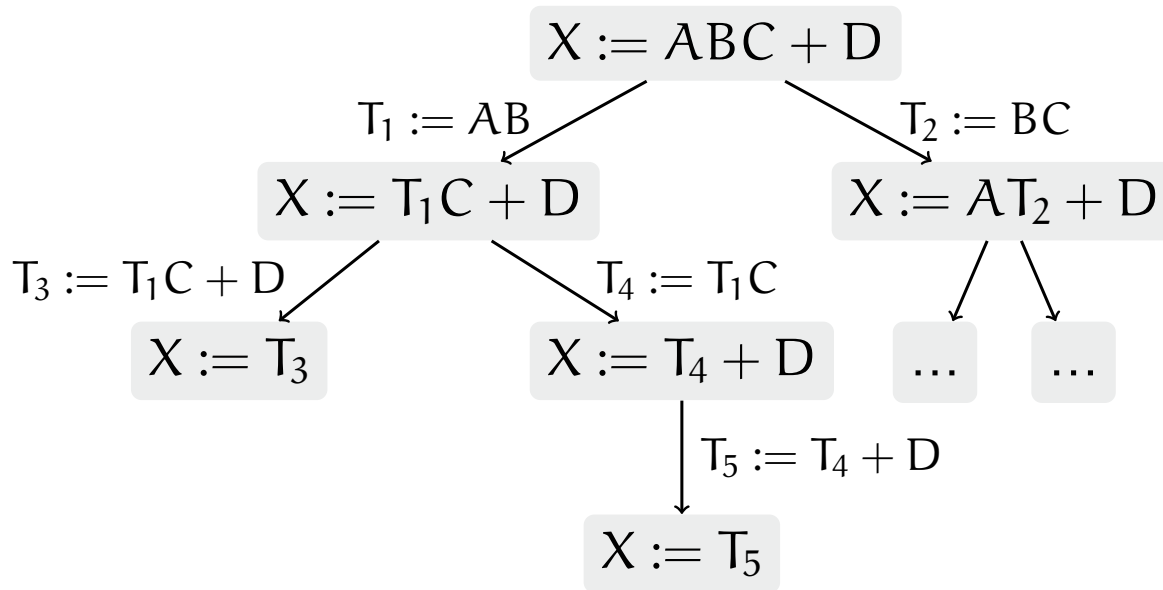


Derivation Graph

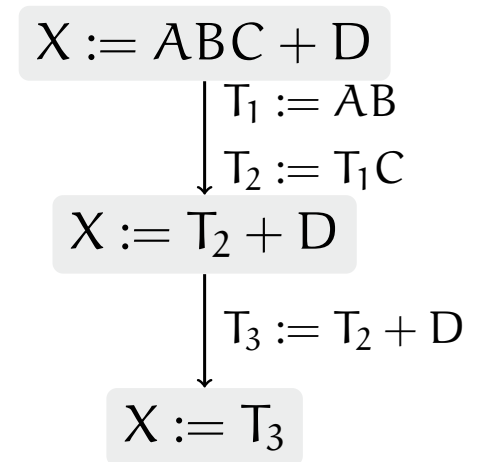


Derivation Graph

Exhaustive

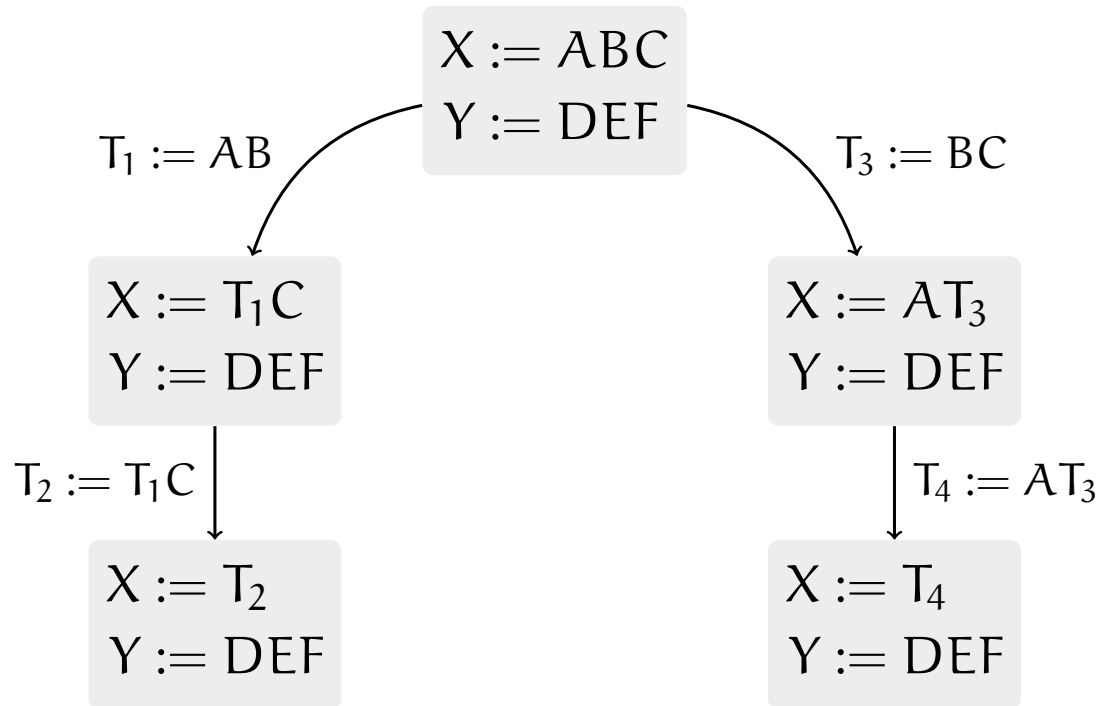


Constructive



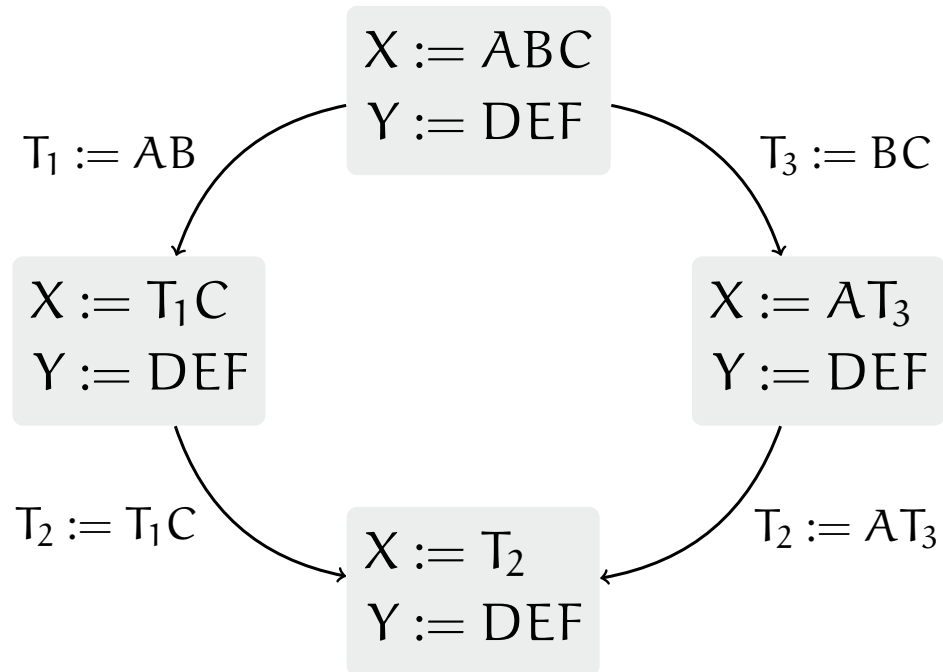
Derivation Graph

Reducing Redundancy



Derivation Graph

Reducing Redundancy



Results

Example: $w := AB^{-1}c$

Naive

$w = A * \text{inv}(B) * c$

Recommended

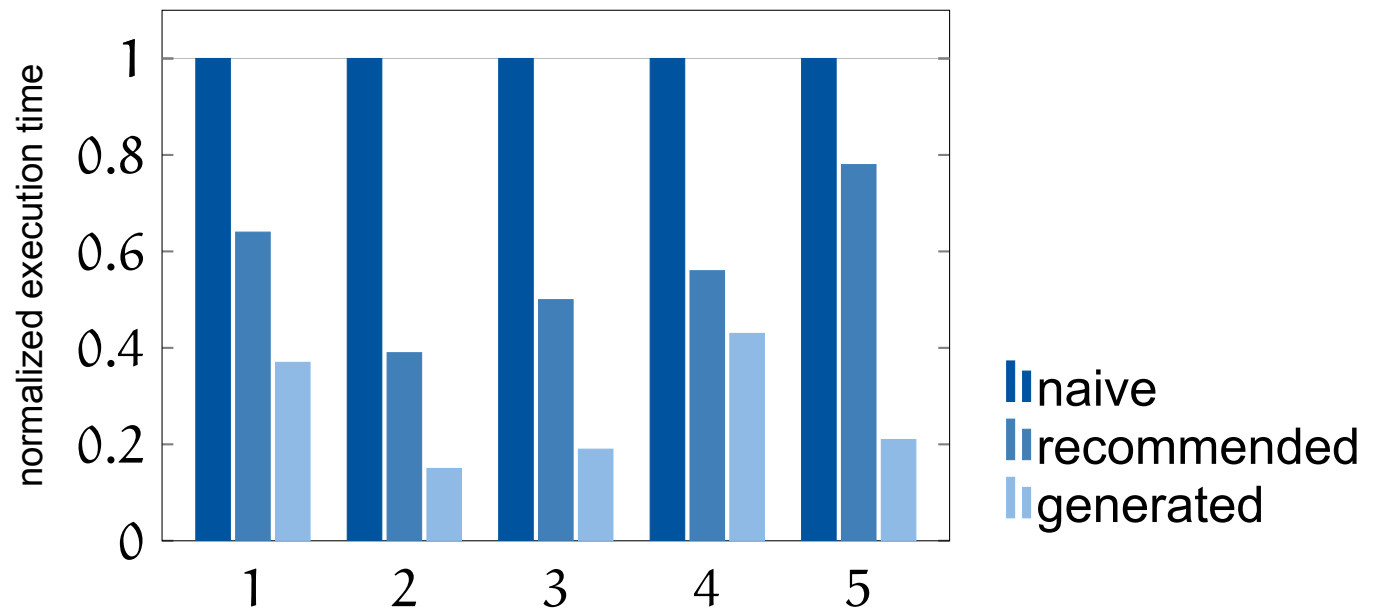
$w = A * (B \setminus c)$

Generated

```
m10 = A; m11 = B; m12 = c;
potrf!('L', m11)
trsv!('L', 'N', 'N', m11, m12)
trsv!('L', 'T', 'N', m11, m12)
m13 = Array{Float64}(10)
gemv!('N', 1.0, m10, m12, 0.0, m13)
w = m13
```

Results

#	Example	code gen time (ms)
1	$b := (X^T X)^{-1} X^T y$	37
2	$b := (X^T M^{-1} X)^{-1} X^T M^{-1} y$	430
3	$W := A^{-1} B C D^{-T} E F$	9
4	$X := A B^{-1} C; Y := D B^{-1} A^T$	17
5	$x := W(A^T(A W A^T)^{-1} b - c)$	537



References

- [AB⁺99] Edward Anderson, Zhaojun Bai, et al. *LAPACK Users' guide*, volume 9. SIAM, 1999.
- [DDC⁺90] Jack J. Dongarra, Jeremy Du Croz, et al. A set of Level 3 Basic Linear Algebra Subprograms. *ACM TOMS*, 16(1):1–17, 1990.