

Software for tensor computations: What is happening???

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Schloss Dagstuhl



High Performance and
Automatic Computing



UMEÅ UNIVERSITY



HPC2N

Ongoing survey

“The Landscape Of Software For Tensor Computations”
with C. Psarras, L. Karlsson, J. Li

<https://arxiv.org/pdf/2103.13756.pdf>

DatM: Data Manipulation **EWOps**: Element-Wise Operations **Con**: Contractions
SpecCon: Specific Contractions **Decomp**: Decompositions

ID	Package Name	Functionality					Type	Platform	Language
		DatM	EWOps	SpecCon	Con	Decomp			
0	Acrotensor	—	—	✓	✓	—	D	C, G	C++
1	AdaTM	—	—	✓	—	✓	S	C	C
2	Boost.uBlas.Tensor	✓	✓	✓	✓	—	D	C	C++
3	COGENT	—	—	✓	✓	—	D	G	Python → C
4	COMET	—	—	✓	✓	—	S	C	C++ → C++
5	CoTenGra	—	—	✓	✓	—	D	C, D, G	Python
6	CP-CALS	—	—	✓	—	✓	D	C, G	C++, Mat ⁱ
7	CSTF	—	—	—	—	✓	S	D	Scala
8	CuTensor	✓	✓	✓	✓	—	D	G	C, CUDA
9	cuTT	✓	—	—	—	—	D	G	C++, CUDA
10	Cyclops	✓	✓	✓	✓	—	S	C, D, G	C++
11	DFacTo	—	—	—	—	✓	S	C, D	C++
12	Eigen Tensor	✓	✓	✓	✓	—	D	C, G	C++
13	ExaTN	✓	✓	✓	✓	✓	D	C, D, G	C++, Py ⁱ
14	Fastor	✓	✓	✓	✓	—	D	C	C++
15	FTensor	✓	✓	✓	✓	—	D	C	C++
16	Genten	—	—	—	—	✓	D, S	C, G	C++
17	GigaTensor	—	—	—	—	✓	S	C, D	Unknown

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18	HPTT	✓	—	—	—	—	D	C	C++, Python
19	ITensor	—	✓	✓	✓	✓	D, BS	C, G ^x	C++, Julia
20	libtensor	—	—	✓	✓	—	D, BS	C	C++
21	Ltensor	—	—	✓	✓	—	D	C	C++
22	MATLAB	✓	✓	—	—	—	D	C	Matlab
23	MultiArray	✓	—	—	—	—	D	C	C++
24	multiway	—	—	—	—	✓	D	C	R
25	N-way toolbox	—	—	—	—	✓	D	C	Matlab
26	NCON	—	—	✓	✓	—	D	C	Matlab
27	netcon	—	—	✓	✓	—	D	C	Matlab
28	NumPy	✓	✓	✓	✓	—	D	C	Python
29	Ocean	✓	✓	—	—	—	D	C, G	C, Py ⁱ
30	ParCube	—	—	—	—	✓	S	C	Matlab
31	ParTensor	—	—	—	—	✓	D	C, G	C++
32	ParTI!	✓	✓	✓	—	✓	S	C, G	C, CUDA, M
33	PLANC	—	—	—	—	✓	D	C, D	C++
34	PLS toolbox	—	—	—	—	✓	D	C	Matlab
35	Pytensor	✓	✓	✓	✓	✓	D, S	C	Python

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36	PyTorch	✓	✓	✓	✓	—	D, S	C, G	Python, C++
37	quimb	—	—	✓	✓	—	D	C, D, G	Python
38	rTensor	✓	✓	✓	—	✓	D	C	R
39	rTensor (randomized)	—	—	—	—	✓	D	C	Python
40	scikit-tensor	✓	✓	✓	—	✓	D, S	C	Python
41	Scikit-TT	—	—	—	—	✓	D	C	Python
42	SPALS	—	—	—	—	✓	S	C	C++
43	SPARTan	—	—	—	—	✓	S	C	Matlab
44	SPLATT	—	—	✓	—	✓	S	C, D	C, C++, Oct
45	SuSMoST	—	—	—	—	✓	D	C	Python
46	T3F	✓	✓	—	—	✓	D	C, G	Python
47	TACO	✓	✓	✓	✓	—	D, S	C, G	C++, C++ →
48	TAL_SH	✓	✓	✓	✓	—	D	C, G	C, C++, Fort
49	TBlis	✓	✓	✓	✓	—	D	C	C++
50	TCCG	—	—	✓	✓	—	D	C	C++
51	TCL	—	—	✓	✓	—	D	C	C++, Python
52	TDALAB	—	—	—	—	✓	D, S	C	Matlab, GU
53	TeNPy	—	—	—	—	✓	D	C	Python

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54	Tensor Fox	—	—	—	—	✓	D, S	C	Python, Ma
55	Tensor package	—	—	—	—	✓	D	C	Matlab
56	Tensor Toolbox	✓	✓	✓	✓	✓	D, S	C	Matlab
57	tensor_decomposition	—	—	—	—	✓	D	C, D	Python
58	TensorBox	—	—	—	—	✓	D, S	C	Matlab
59	TensorD	—	—	—	—	✓	D	C, G	Python
60	TensorFlow	✓	✓	✓	✓	—	D, S	C, D, G	C++, Python
61	TensorLab	—	—	—	—	✓	D, S	C	Matlab
62	TensorLy	✓	✓	✓	✓	✓	D	C, G	Python
63	TensorNetwork	—	—	✓	✓	—	D, S	C, G	Python
64	TensorOperations.jl	✓	✓	✓	✓	—	D	C, G	Julia
65	TensorTrace	—	—	✓	✓	—	D	C	GUI → Py,
66	Three-Way	—	—	✓	✓	✓	D	C	R
67	TiledArray	✓	✓	✓	✓	—	D, BS	C, D	C++
68	tncontract	—	—	✓	✓	—	D	C	Python
69	TNR	—	—	—	—	✓	D	C	Matlab
70	TorchMPS	—	—	✓	✓	—	D	C	Python
71	TT-Toolbox	✓	✓	—	—	✓	D	C, D ^x , G ^x	Matlab, Pyt

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72	TTC	✓	—	—	—	—	D	C	Python → C
73	TTV	—	—	✓	—	—	D	C	C++
74	TVM	—	✓	—	—	—	D, S	C, G	Python
75	Uni10	✓	✓	✓	✓	—	D	C, G ^x	C++
76	xerus	—	—	✓	✓	✓	D, S	C,	C++

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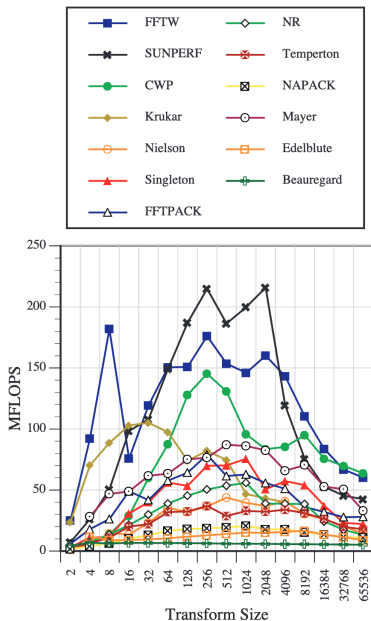
- ▶ 1) Why?!
- ▶ 2) Is there a way out?

Have we seen this before?

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- ▶ Libraries for computing FFTs, prior to FFTW

FFT: 1 single op, many different algs,
different datatypes, 2 languages;
⇒ 1 small team (users) took over



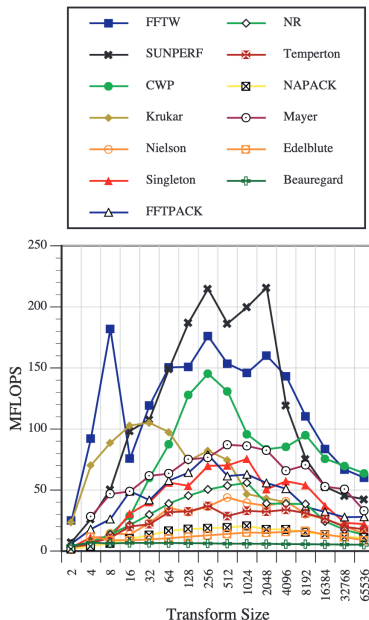
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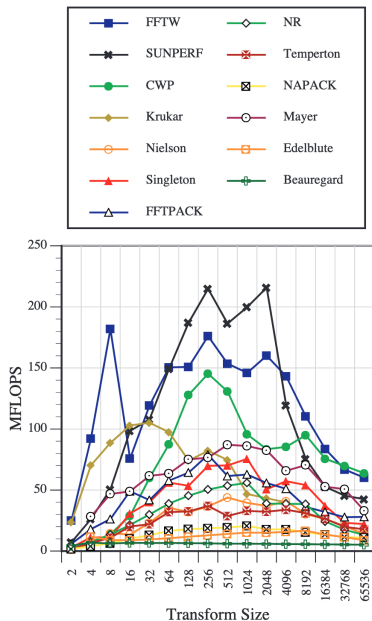
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- ▶ Different routes to “convergence”
What about Tensorland?



Matrices vs. Tensors

Historical overview

Linear Algebra Libraries: 1970s

"Basic Linear Algebra Subprograms for FORTRAN usage", ACM TOMS, 1979

BLAS-1

Linear Algebra Libraries: 1980s

BLAS-2: Mat-vec ops, ACM TOMS 1988.

BLAS-3: mat-mat ops, ACM TOMS 1990

BLAS-1, BLAS-2, BLAS-3

Linear Algebra Libraries: 1990s

Solvers & eigensolvers, 1992

LAPACK

BLAS-1, BLAS-2, BLAS-3

Linear Algebra Libraries: 1990s

Distributed Memory, 1995, 1997

ScaLAPACK, PLAPACK, ...

LAPACK

BLAS-1, BLAS-2, BLAS-3

Linear Algebra Libraries: 1990s

Dense & Sparse, 1997

PETSc, ...

ScaLAPACK, PLAPACK, ...

LAPACK

BLAS-1, BLAS-2, BLAS-3

Linear Algebra Libraries

and then more!

PETSc, Trilinos, ...

ScaLAPACK, PLAPACK, Elemental, ...

LAPACK, Plasma, SuperMatrix, Magma, ...

BLAS-1, BLAS-2, BLAS-3, ATLAS, BTO-BLAS, BLIS, ...

(Dense) Linear Algebra Libraries

Salient features

- ▶ Community effort. Standardized interface
- ▶ Careful organization: support routines, linear-systems, eigen-decompositions
- ▶ Clear layering: functionality, parallelism

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But

- ▶ Rigid interface
- ▶ Black-box nature
- ▶ Often sub-optimal at small scale

$$K_k := P_k^b H^T (H P_k^b H^T + R)^{-1}; \quad x_k^a := x_k^b + K_k (z_k - H x_k^b); \quad P_k^a := (I - K_k H) P_k^b$$

$$\begin{cases} C_{\dagger} := P C P^T + Q \\ K := C_{\dagger} H^T (H C_{\dagger} H^T)^{-1} \end{cases}$$

$$\Lambda := S(S^T A W A S)^{-1} S^T; \quad \Theta := \Lambda A W; \quad M_k := X_k A - I \\ X_{k+1} := X_k - M_k \Theta - (M_k \Theta)^T + \Theta^T (A X_k A - A) \Theta$$

$$x := A(B^T B + A^T R^T \Lambda R A)^{-1} B^T B A^{-1} y \quad \dots \quad E := Q^{-1} U (I + U^T Q^{-1} U)^{-1} U^T$$



MUL ADD MOV
 MOVAPD
 VFMADDPD ...

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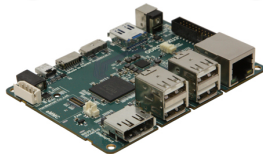
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$$y := \alpha x + y \quad LU = A \quad \dots \quad C := \alpha AB + \beta C$$

$$X := A^{-1} B \quad C := AB^T + BA^T + C \quad X := L^{-1} M L^{-T} \quad QR = A$$

...  BLAS  LAPACK  ...



MUL ADD MOV

MOVAPD

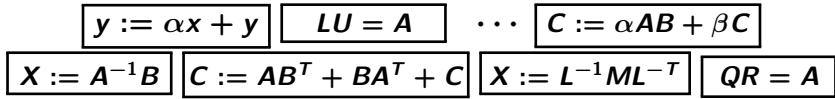
VFMADDPD ...

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... **BLAS** **LAPACK** ...



- MUL
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- ...

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LINEAR ALGEBRA MAPPING PROBLEM ("LAMP")

$$\begin{array}{ccccccc} \boxed{y := \alpha x + y} & \boxed{LU = A} & \cdots & \boxed{C := \alpha AB + \beta C} & & & \\ \boxed{X := A^{-1} B} & \boxed{C := AB^T + BA^T + C} & \boxed{X := L^{-1} M L^{-T}} & \boxed{QR = A} & & & \end{array}$$

... **BLAS** **LAPACK** ...

- C. Psarras, H. Barthels, P. Bientinesi, [arXiv:1911.09421]
"The Linear Algebra Mapping Problem. Current state of linear algebra languages and libraries".
- A. Sankaran, N.A. Alashti, C. Psarras, P. Bientinesi, [arXiv:2202.09888]
"Benchmarking the Linear Algebra Awareness of TensorFlow and PyTorch".
- H. Barthels, C. Psarras, P. Bientinesi, [arXiv:1912.12924]
"Linnea: Automatic Generation of Efficient Linear Algebra Programs", ACM TOMS, 2021.

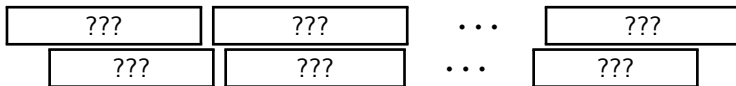
Tensors

Tensor App #1

Tensor App #2

...

Tensor App #N



BLAS
LAPACK



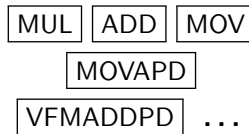
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...



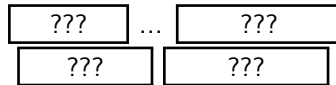
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but...

Comp. Physics
Comp. Chemistry

Data Science
Machine Learning

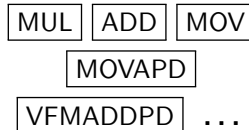
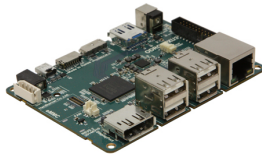


BLAS
LAPACK

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- ▶ (At least) Two separate worlds

¹With notable differences.

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- ▶ Computational physics / chemistry

Tensor = Multi-linear operator

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- ▶ Data science

- Tensor = Collection of data

- Decompositions = Generalization of matrix factorizations¹

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Tensor computations

- ▶ (At least) Two separate worlds
 - ▶ Computational physics / chemistry
 - Tensor = Multi-linear operator
 - Contractions = Generalization of matrix-matrix product
 - ▶ Data science
 - Tensor = Collection of data
 - Decompositions = Generalization of matrix factorizations¹
- ▶ Terminology and notation vary (and conflict) even within one world
- ▶ Very few software efforts cut across the boundary

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Tensors, presently

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A jungle of independent libraries and packages, in a variety of languages
Massive redundancy: replication of effort, low performance
- ▶ Application-driven development:
Publications scattered among different fields
Re-invention of the wheel

Representative operations – building blocks candidates

Data layout operations

- ▶ Reshape
- ▶ Permute / transpose
- ▶ Sort (sparse)
- ▶ Convert data layout
- ▶ Partition
- ▶ Distribute
- ▶ ...

Arithmetic operations

- ▶ Add, subtract, scale
- ▶ Inner product
- ▶ Norms
- ▶ Element-wise operations
- ▶ Tensor-times-vector (TTV)
- ▶ Tensor-times-matrix (TTM)
- ▶ MTTKRP
- ▶ Contractions
- ▶ ...

Decompositions

- ▶ CP
(CANDECOMP/PARAFAC)
- ▶ Tucker
- ▶ INDSCAL
- ▶ PARAFAC2
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- ▶ DEDICOM
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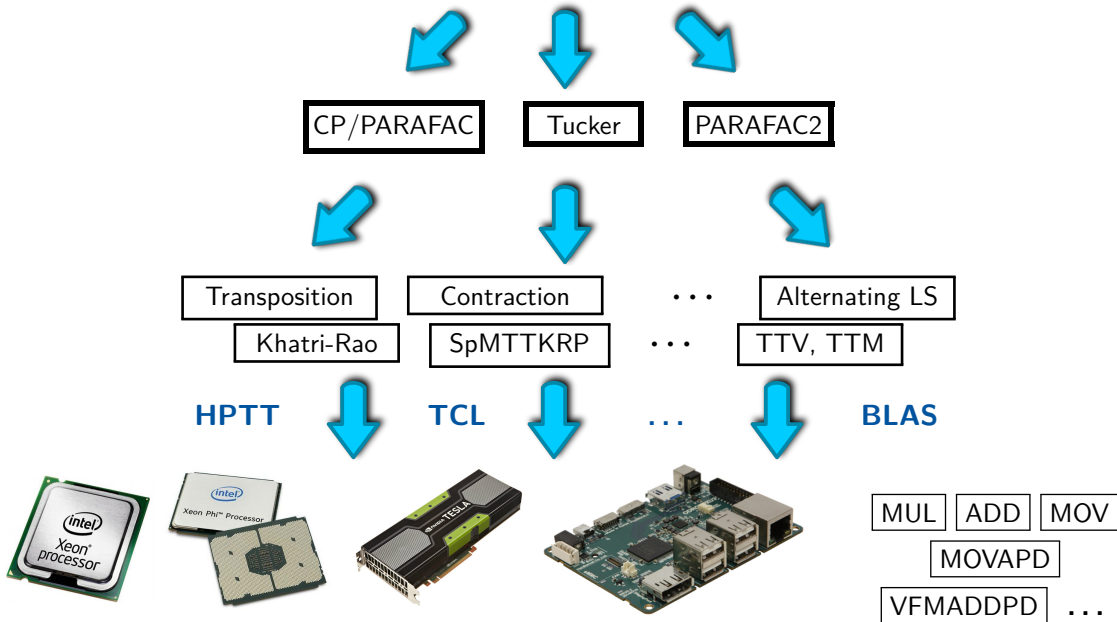
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Where to draw the boundaries?

E.g., where does the “T-BLAS” end and the “T-LAPACK” begin?

2-level "solution"

Chromatography-MS



Algorithms for CP (PARAFAC) decomposition

Hence all the different libraries

▶ Algebraic algorithms

- ▶ Generalized Rank Annihilation Method
- ▶ Direct TriLinear Decomposition
- ▶ The “algebraic algorithm”
by Domanov and De Lathauwer
- ▶ The “simpler algorithm”
by Pimentel-Alarcón
- ▶ ...

▶ Alternating optimization algorithms

- ▶ Alternating Least Squares
- ▶ Fast ALS
- ▶ Hierarchical ALS
- ▶ Regularized ALS
- ▶ ...

▶ All-at-once optimization algorithms

- ▶ Gradient descent
- ▶ (Damped) Gauss–Newton
- ▶ Nonlinear CG, GMRES
- ▶ Quasi-Newton (e.g., L-BFGS)
- ▶ ...

▶ Enhancements

- ▶ Line search
- ▶ Compression
- ▶ Randomization
- ▶ Transient constraints
- ▶ ...

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Is a computational hierarchy even possible? Or is optimality achieved via specialized kernels?

Also ... one vs. many problem instances

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Coupled-Cluster methods

$$\tilde{\tau}_{ij}^{ab} = t_{ij}^{ab} + \frac{1}{2} P_b^a P_j^i t_i^a t_j^b,$$

$$\tilde{F}_e^m = f_e^m + \sum_{fn} v_{ef}^{mn} t_n^f,$$

$$\tilde{F}_e^a = (1 - \delta_{ae}) f_e^a - \sum_m \tilde{F}_e^m t_m^a - \frac{1}{2} \sum_{mnf} v_{ef}^{mn} t_{mn}^{af} + \sum_{fn} v_{ef}^{an} t_n^f,$$

$$\tilde{F}_i^m = (1 - \delta_{mi}) f_i^m + \sum_e \tilde{F}_e^m t_i^e + \frac{1}{2} \sum_{nef} v_{ef}^{mn} t_{in}^{ef} + \sum_{fn} v_{if}^{mn} t_n^f,$$

$$\tilde{W}_{ei}^{mn} = v_{ei}^{mn} + \sum_f v_{ef}^{mn} t_i^f,$$

$$\tilde{W}_{ij}^{mn} = v_{ij}^{mn} + P_j^i \sum_e v_{ie}^{mn} t_j^e + \frac{1}{2} \sum_{ef} v_{ef}^{mn} \tau_{ij}^{ef},$$

$$\tilde{W}_{ie}^{am} = v_{ie}^{am} - \sum_n \tilde{W}_{ei}^{mn} t_n^a + \sum_f v_{ef}^{ma} t_i^f + \frac{1}{2} \sum_{nf} v_{ef}^{mn} t_{in}^{af},$$

$$\tilde{W}_{ij}^{am} = v_{ij}^{am} + P_j^i \sum_e v_{ie}^{am} t_j^e + \frac{1}{2} \sum_{ef} v_{ef}^{am} \tau_{ij}^{ef},$$

$$z_i^a = f_i^a - \sum_m \tilde{F}_i^m t_m^a + \sum_e f_e^a t_i^e + \sum_{em} v_{ei}^{ma} t_m^e + \sum_{em} v_{im}^{ae} \tilde{F}_e^m + \frac{1}{2} \sum_{efm}$$

$$z_{ij}^{ab} = v_{ij}^{ab} + P_j^i \sum_e v_{ie}^{ab} t_j^e + P_b^a P_j^i \sum_{me} \tilde{W}_{ie}^{am} t_{mj}^{eb} - P_b^a \sum_m \tilde{W}_{ij}^{am} t_m^b + P$$

credits to D. Matthews, E. Solomonik, J. Stanton, and J. Gauss

Also ... one vs. many problem instances

Coupled-Cluster methods

$$\tilde{\tau}_{ij}^{ab} = t_{ij}^{ab} + \frac{1}{2} P_b^a P_j^i t_i^a t_j^b,$$

$$\tilde{F}_e^m = f_e^m + \sum_{fn} v_{ef}^{mn} t_n^f,$$

$$\tilde{F}_e^a = (1 - \delta_{ae}) f_e^a - \sum_m \tilde{F}_e^m t_m^a - \frac{1}{2} \sum_{mnf} v_{ef}^{mn} t_{mn}^{af} + \sum_{fn} v_{ef}^{an} t_n^f,$$

$$\tilde{F}_i^m = (1 - \delta_{mi}) f_i^m + \sum_e \tilde{F}_e^m t_i^e + \frac{1}{2} \sum_{nef} v_{ef}^{mn} t_{in}^{ef} + \sum_{fn} v_{if}^{mn} t_n^f,$$

$$\tilde{W}_{ei}^{mn} = v_{ei}^{mn} + \sum_f v_{ef}^{mn} t_i^f,$$

$$\tilde{W}_{ij}^{mn} = v_{ij}^{mn} + P_j^i \sum_e v_{ie}^{mn} t_j^e + \frac{1}{2} \sum_{ef} v_{ef}^{mn} \tau_{ij}^{ef},$$

$$\tilde{W}_{ie}^{am} = v_{ie}^{am} - \sum_n \tilde{W}_{ei}^{mn} t_n^a + \sum_f v_{ef}^{ma} t_i^f + \frac{1}{2} \sum_{nf} v_{ef}^{mn} t_{in}^{af},$$

$$\tilde{W}_{ij}^{am} = v_{ij}^{am} + P_j^i \sum_e v_{ie}^{am} t_j^e + \frac{1}{2} \sum_{ef} v_{ef}^{am} \tau_{ij}^{ef},$$

$$z_i^a = f_i^a - \sum_m \tilde{F}_i^m t_m^a + \sum_e f_e^a t_i^e + \sum_{em} v_{ei}^{ma} t_m^e + \sum_{em} v_{im}^{ae} \tilde{F}_e^m + \frac{1}{2} \sum_{efm}$$

$$z_{ij}^{ab} = v_{ij}^{ab} + P_j^i \sum_e v_{ie}^{ab} t_j^e + P_b^a P_j^i \sum_{me} \tilde{W}_{ie}^{am} t_{mj}^{eb} - P_b^a \sum_m \tilde{W}_{ij}^{am} t_m^b + P$$

Finite Element 3D diffusion operator

```
TE.BeginMultiKernelLaunch();
TE("T2_e_i1_i2_k3 = B_k3_i3 X_e_i1_i2_i3", T2, B, X);
TE("T1_e_i1_k2_k3 = B_k2_i2 T2_e_i1_i2_k3", T1, B, T2);
TE("U1_e_k1_k2_k3 = G_k1_i1 T1_e_i1_k2_k3", U1, G, T1);
TE("T1_e_i1_k2_k3 = G_k2_i2 T2_e_i1_i2_k3", T1, G, T2);
TE("U2_e_k1_k2_k3 = B_k1_i1 T1_e_i1_k2_k3", U2, B, T1);
TE("T2_e_i1_i2_k3 = G_k3_i3 X_e_i1_i2_i3", T2, G, X);
TE("T1_e_i1_k2_k3 = B_k2_i2 T2_e_i1_i2_k3", T1, B, T2);
TE("U3_e_k1_k2_k3 = B_k1_i1 T1_e_i1_k2_k3", U3, B, T1);
TE("Z_m_e_k1_k2_k3 = U_n_e_k1_k2_k3 D_e_m_n_k1_k2_k3", Z, U,
TE("T1_e_i3_k1_k2 = B_k3_i3 Z1_e_k1_k2_k3", T1, B, Z1);
TE("T2_e_i2_i3_k1 = B_k2_i2 T1_e_i3_k1_k2", T2, B, T1);
TE("Y_e_i1_i2_i3 = G_k1_i1 T2_e_i2_i3_k1", Y, G, T2);
TE("T1_e_i3_k1_k2 = B_k3_i3 Z2_e_k1_k2_k3", T1, B, Z2);
TE("T2_e_i2_i3_k1 = G_k2_i2 T1_e_i3_k1_k2", T2, G, T1);
TE("Y_e_i1_i2_i3 += B_k1_i1 T2_e_i2_i3_k1", Y, B, T2);
TE("T1_e_i3_k1_k2 = G_k3_i3 Z3_e_k1_k2_k3", T1, G, Z3);
TE("T2_e_i2_i3_k1 = B_k2_i2 T1_e_i3_k1_k2", T2, B, T1);
TE("Y_e_i1_i2_i3 += B_k1_i1 T2_e_i2_i3_k1", Y, B, T2);
TE.EndMultiKernelLaunch();
```

credits to D. Matthews, E. Solomonik, J. Stanton, and J. Gauss

credits to A. Fisher – <https://github.com/LLNL/acrotensor>

Also ... one vs. many problem instances

- ▶ BLAS and LAPACK built and optimized for single problems
Only much much later “streaming BLAS”, “batched BLAS”

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Huge opportunities for multi-instance / multi-problem optimizations.

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Huge opportunities for multi-instance / multi-problem optimizations.

Example:

C. Psarras, L. Karsson, R. Bro, P. Bientinesi, [arXiv:2010.04678v2]
“Concurrent Alternating Least Squares for multiple simultaneous Canonical Polyadic Decompositions”, ACM TOMS.

Summary & questions

Matrices

Tensors

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Driver	performance, HW	applications

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- ▶ “DEV people”: What does it take to kickstart a community effort? ... Dagstuhl?
- ▶ “APP people”: What would it take for you to consider using different libraries, possibly a different language?