

# Goal-oriented and Modular Stability Analysis

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Conference on Numerical Linear Algebra:  
Perturbation, Performance and Portability  
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- 1 Motivation
- 2 Formal Derivation Techniques
- 3 Loop-Invariants
- 4 Worksheet
- 5 Analyses
- 6 Blocked LU

$$AX + XB = C$$

- **R.H. Bartels, G.W. Stewart.** *Solution of the matrix equation  $AX + XB = C$*   
Communications of the ACM, **1972**

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- **R.H. Bartels, G.W. Stewart.** *Solution of the matrix equation  $AX + XB = C$*   
Communications of the ACM, **1972**
- B. Kågström, P. Poromaa. *Distributed and shared memory block algorithms for the triangular Sylvester equation [..]*  
SIMAX, 1992
- M. Marqués, R. Van de Geijn and V. Hernández. *Parallel algorithms for the triangular Sylvester equation.*  
3rd SIAM Conference [..] 1993
- B. Kågström, P. Poromaa. *LAPACK-style algorithms and software for solving the generalized Sylvester equation [..]*  
TOMS, 1996
- I. Jonsson, B. Kågström. *Recursive blocked algorithms [..]. Part I: one-sided and coupled Sylvester [..]*  
TOMS, 2002
- R. Granat, B. Kagstrom, and P. Poromaa. *Parallel ScaLAPACK-style algorithms for solving continuous-time Sylvester [..]*  
EuroPar 2003

- FLAME project
- E. Quintana-Ortí, R. van de Geijn: 16 algorithms

$$AX + XB = C \quad \equiv \quad X = \Omega(A, B, C)$$

Partition  $\star \in \{A, B, C\}$  as  $\left( \begin{array}{c|c} \star_{TL} & \star_{TR} \\ \star_{BL} & \star_{BR} \end{array} \right)$  where  $A_{BR}, B_{TL}, C_{BL}$  are  $0 \times 0$

While  $size(C_{TL}) < size(C)$  do

  Repartition

$$\left( \begin{array}{c|c} C_{TL} & C_{TR} \\ \hline C_{BL} & C_{BR} \end{array} \right) \rightarrow \left( \begin{array}{c|c|c} C_{00} & C_{01} & C_{02} \\ \hline C_{10} & C_{11} & C_{12} \\ \hline C_{20} & C_{21} & C_{22} \end{array} \right), \left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right) \rightarrow \left( \begin{array}{c|c|c} A_{00} & A_{01} & A_{02} \\ \hline A_{10} & A_{11} & A_{12} \\ \hline A_{20} & A_{21} & A_{22} \end{array} \right), \dots$$

Algorithm 1

$$\begin{aligned} C_{10} &:= C_{10} - A_{12} C_{20} \\ C_{10} &:= \Omega(A_{11}, B_{00}, C_{10}) \\ C_{21} &:= C_{21} - C_{20} B_{01} \\ C_{21} &:= \Omega(A_{22}, B_{11}, C_{21}) \\ C_{11} &:= C_{11} - A_{12} C_{21} - C_{10} B_{01} \\ C_{11} &:= \Omega(A_{11}, B_{11}, C_{11}) \end{aligned}$$

...

$$\begin{aligned} C_{10} &:= C_{10} - A_{12} C_{20} \\ C_{10} &:= \Omega(A_{11}, B_{00}, C_{10}) \\ C_{11} &:= C_{11} - C_{10} B_{01} - A_{12} C_{21} \\ C_{11} &:= \Omega(A_{11}, B_{11}, C_{11}) \\ C_{12} &:= C_{12} - C_{10} B_{02} - C_{11} B_{12} \\ C_{12} &:= C_{12} - A_{12} C_{22} \\ C_{12} &:= \Omega(A_{11}, B_{22}, C_{12}) \end{aligned}$$

Algorithm 16

$$\begin{aligned} C_{11} &:= C_{11} - C_{10} B_{01} \\ C_{11} &:= \Omega(A_{11}, B_{11}, C_{11}) \\ C_{01} &:= C_{01} - C_{00} B_{01} - A_{01} C_{11} \\ C_{01} &:= \Omega(A_{00}, B_{11}, C_{01}) \\ C_{12} &:= C_{12} - C_{10} B_{02} - C_{11} B_{12} \\ C_{12} &:= \Omega(A_{11}, B_{22}, C_{12}) \\ C_{02} &:= C_{02} - A_{01} C_{12} \end{aligned}$$

  Continue

$$\left( \begin{array}{c|c} C_{TL} & C_{TR} \\ \hline C_{BL} & C_{BR} \end{array} \right) \leftarrow \left( \begin{array}{c|c|c} C_{00} & C_{01} & C_{02} \\ \hline C_{10} & C_{11} & C_{12} \\ \hline C_{20} & C_{21} & C_{22} \end{array} \right), \left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right) \rightarrow \left( \begin{array}{c|c|c} A_{00} & A_{01} & A_{02} \\ \hline A_{10} & A_{11} & A_{12} \\ \hline A_{20} & A_{21} & A_{22} \end{array} \right), \dots$$

endwhile

## Partition

$$A \rightarrow \left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right)$$

where  $A_{TL}$  is empty

While  $A_{TL} \langle \rangle A$

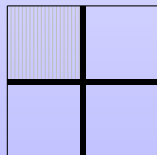
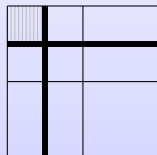
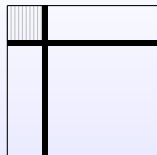
## Repartition

$$\left\{ \left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right) \rightarrow \left( \begin{array}{c|c} A_{00} & (A_{01} \ A_{02}) \\ \hline (A_{10}) & \begin{pmatrix} A_{11} & A_{12} \end{pmatrix} \\ A_{20} & \begin{pmatrix} A_{21} & A_{22} \end{pmatrix} \end{array} \right) \right\}$$

## Continue with

$$\left\{ \left( \begin{array}{c|c} A_{00} & A_{01} \\ \hline A_{10} & A_{11} \\ A_{20} & A_{21} \end{array} \right) \middle| \begin{pmatrix} A_{02} \\ A_{12} \end{pmatrix} \right\} \rightarrow \left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right)$$

end while



<u>Algorithm 1</u>	...	<u>Algorithm 16</u>
$C_{10} := C_{10} - A_{12}C_{20}$ $C_{10} := \Omega(A_{11}, B_{00}, C_{10})$ $C_{21} := C_{21} - C_{20}B_{01}$ $C_{21} := \Omega(A_{22}, B_{11}, C_{21})$ $C_{11} := C_{11} - A_{12}C_{21} - C_{10}B_{01}$ $C_{11} := \Omega(A_{11}, B_{11}, C_{11})$	$C_{10} := C_{10} - A_{12}C_{20}$ $C_{10} := \Omega(A_{11}, B_{00}, C_{10})$ $C_{11} := C_{11} - C_{10}B_{01} - A_{12}C_{21}$ $C_{11} := \Omega(A_{11}, B_{11}, C_{11})$ $C_{12} := C_{12} - C_{10}B_{02} - C_{11}B_{12}$ $C_{12} := C_{12} - A_{12}C_{22}$ $C_{12} := \Omega(A_{11}, B_{22}, C_{12})$	$C_{11} := C_{11} - C_{10}B_{01}$ $C_{11} := \Omega(A_{11}, B_{11}, C_{11})$ $C_{01} := C_{01} - C_{00}B_{01} - A_{01}C_{11}$ $C_{01} := \Omega(A_{00}, B_{11}, C_{10})$ $C_{12} := C_{12} - C_{10}B_{02} - C_{11}B_{12}$ $C_{12} := \Omega(A_{11}, B_{22}, C_{12})$ $C_{02} := C_{02} - A_{01}C_{12}$

Good performance → TOMS submission

<p style="text-align: center; margin: 0;"><u>Algorithm 1</u></p> $C_{10} := C_{10} - A_{12}C_{20}$ $C_{10} := \Omega(A_{11}, B_{00}, C_{10})$ $C_{21} := C_{21} - C_{20}B_{01}$ $C_{21} := \Omega(A_{22}, B_{11}, C_{21})$ $C_{11} := C_{11} - A_{12}C_{21} - C_{10}B_{01}$ $C_{11} := \Omega(A_{11}, B_{11}, C_{11})$	<p style="margin: 0;">...</p>	<p style="text-align: center; margin: 0;"><u>Algorithm 16</u></p> $C_{11} := C_{11} - C_{10}B_{01}$ $C_{11} := \Omega(A_{11}, B_{11}, C_{11})$ $C_{01} := C_{01} - C_{00}B_{01} - A_{01}C_{11}$ $C_{01} := \Omega(A_{00}, B_{11}, C_{10})$ $C_{12} := C_{12} - C_{10}B_{02} - C_{11}B_{12}$ $C_{12} := \Omega(A_{11}, B_{22}, C_{12})$ $C_{02} := C_{02} - A_{01}C_{12}$
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Good performance → TOMS submission

Problem: missing error analysis

- Are they all numerically stable? (no!)
- Recursive calls?  $k^2$  stability analyses? hm...
- **Initial Goal:** (dissertation)  
Systematic procedure from algorithm to stability?  
Systematic ⇒ computer algebra system



## Automatic generation of algorithms

$$\{A, L, U \in \mathbb{R}^{n \times n}$$

$$\text{LowerTriUni}(L),$$

$$\text{UpperTri}(U),$$

$$LU = A \}$$
 $\Rightarrow$ 

**Partition**  $A \rightarrow \left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right)$   
 where  $A_{TL}$  is  $0 \times 0$

**While**  $\text{size}(A_{TL}) < \text{size}(A)$  **do**

**Repartition**

$$\left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right) \rightarrow \left( \begin{array}{c|c|c} A_{00} & A_{01} & A_{02} \\ \hline A_{10} & A_{11} & A_{12} \\ \hline A_{20} & A_{21} & A_{22} \end{array} \right)$$


---


$$A_{01} := L_{00}^{-1} A_{01}$$

$$A_{10} := A_{10} U_{00}^{-1}$$

$$A_{11} := \text{LU}(A_{11} - A_{10} A_{01})$$


---

**Continue**

$$\left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right) \leftarrow \left( \begin{array}{c|c|c} A_{00} & A_{01} & A_{02} \\ \hline A_{10} & A_{11} & A_{12} \\ \hline A_{20} & A_{21} & A_{22} \end{array} \right)$$

**endwhile**

## Stability analysis as a matrix operation

- **Operation:**  $LU = A$   
**Input:**  $A$   
**Goal:** find algorithm(s) to compute  $L$  and  $U$

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**Input:**  $A, \check{L}, \check{U}$   
**Input:** algorithm used to compute  $L$  and  $U$   
**Goal:** find algorithm(s) to “compute”  $\Delta A$   
**Goal:** find bounds for  $\|\Delta A\|$  or  $|\Delta A|$

The methodology for generating algorithms can be used for studying their numerical properties too.

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$\text{Sort}( v = \{x_0, x_1, x_2, x_3, \dots, x_n\} )$



Sort(  $v = \{x_0, x_1, x_2, x_3, \dots, x_n\}$  )

**Algorithm:** selection sort

```
for i=0:n,  
    swap( min(v(i:n)), v(i) );  
endfor
```

Sort(  $v = \{x_0, x_1, x_2, x_3, \dots, x_n\}$  )

**Algorithm:** selection sort

```
for i=0:n,  
    swap( min(v(i:n)), v(i) );  
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```

After  $i$ -th iteration:

$$\underbrace{\{v_0, v_1, \dots, v_i\}}_{v_L = \text{sorted}} \mid \underbrace{\{v_{i+1}, v_{i+2}, \dots, v_n\}}_{v_R = \text{to sort}}$$

# Definition: loop-invariant

Example: Sorting

$$\text{Sort}( v = \{x_0, x_1, x_2, x_3, \dots, x_n\} )$$

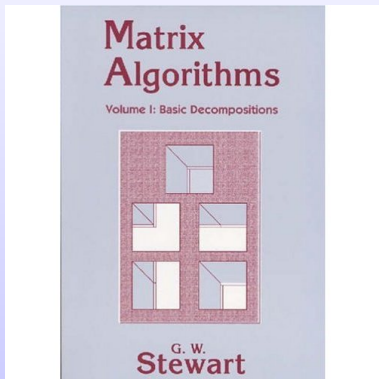
**Algorithm:** selection sort

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for i=0:n,
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**Loop Invariant:**  $v = \{ v_L \mid v_R \} \wedge \text{sorted}(v_L)$



**Partition**  $A \rightarrow \left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right)$   
where  $A_{TL}$  is  $0 \times 0$

**While**  $size(A_{TL}) < size(A)$  **do**

**Repartition**

$$\left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right) \rightarrow \left( \begin{array}{c|c|c} A_{00} & A_{01} & A_{02} \\ \hline A_{10} & A_{11} & A_{12} \\ \hline A_{20} & A_{21} & A_{22} \end{array} \right)$$

$$A_{01} := L_{00}^{-1} A_{01}$$

$$A_{10} := A_{10} U_{00}^{-1}$$

$$A_{11} := \text{LU}(A_{11} - A_{10} A_{01})$$

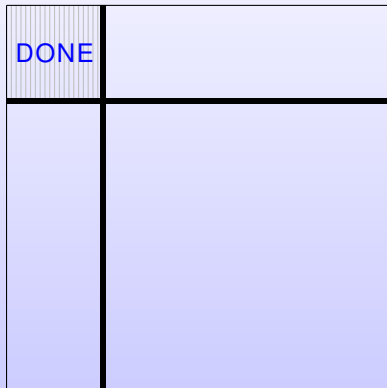
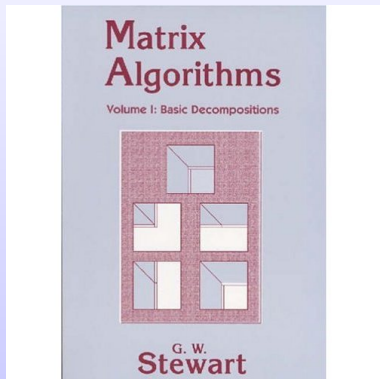
**Continue**

$$\left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right) \leftarrow \left( \begin{array}{c|c|c} A_{00} & A_{01} & A_{02} \\ \hline A_{10} & A_{11} & A_{12} \\ \hline A_{20} & A_{21} & A_{22} \end{array} \right)$$

**endwhile**

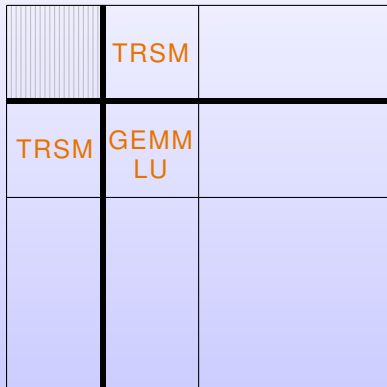
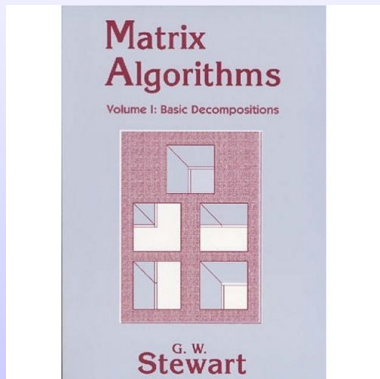
# Example: LU factorization

Iteration i: completed



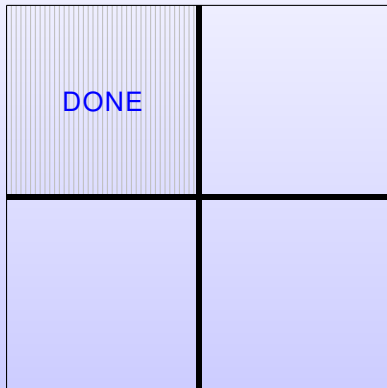
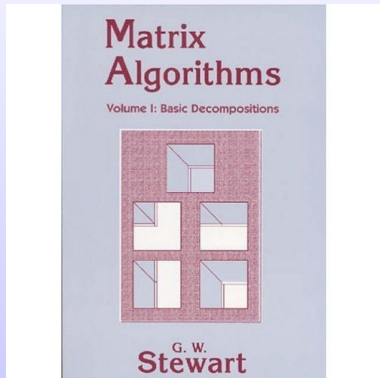
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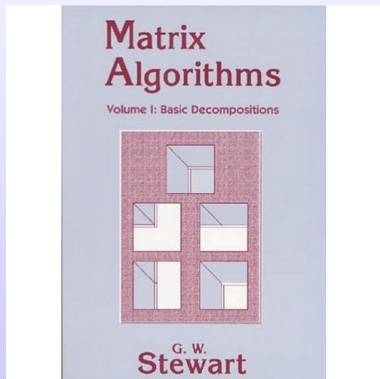
Iteration  $i+1$ : computation



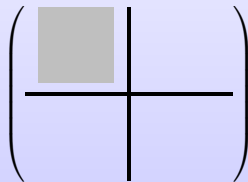
# Example: LU factorization

Iteration  $i+1$ : completed (boundary shift)

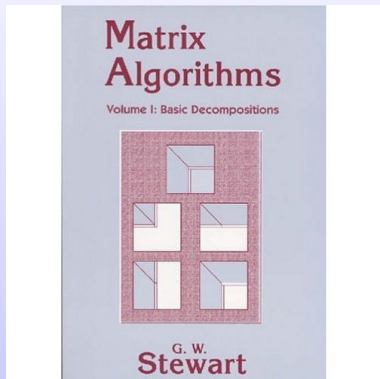




Loop-Invariant = ?

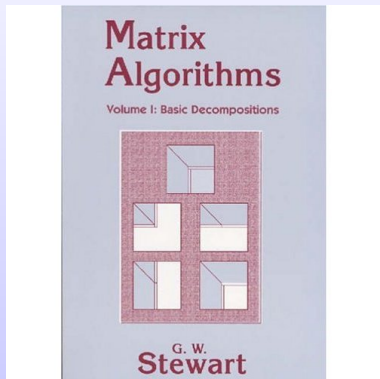






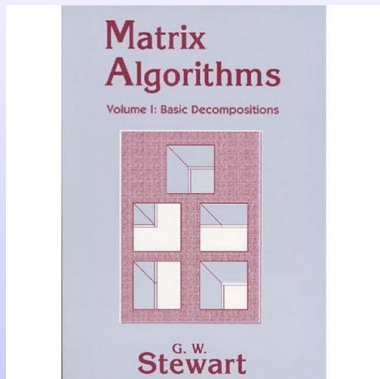
PME( $LU = A$ )

$$\left( \begin{array}{c|c} L_{TL}U_{TL} = A_{TL} & U_{TR} = L_{TL}^{-1}A_{TR} \\ \hline L_{BL} = A_{BL}U_{TL}^{-1} & \begin{array}{l} L_{BR}U_{BR} = \\ A_{BR} - L_{BL}U_{TR} \end{array} \end{array} \right)$$



Loop-Invariant

$$\left( \begin{array}{c|c} L_{TL}U_{TL} = A_{TL} & \\ \hline & \end{array} \right)$$



**Partition**  $A \rightarrow \left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right)$   
where  $A_{TL}$  is  $0 \times 0$

**While**  $size(A_{TL}) < size(A)$  **do**

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$$A_{11} := \text{LU}(A_{11} - A_{10}A_{01})$$

$$A_{12} := (A_{21} - A_{20}A_{01})U_{11}^{-1}$$

$$A_{21} := L_{11}^{-1}(A_{12} - A_{10}A_{02})$$

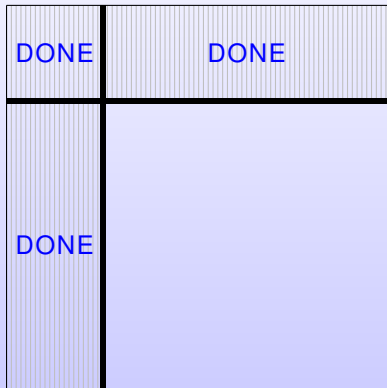
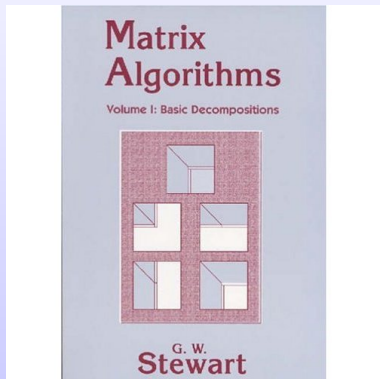
**Continue**

$$\left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right) \leftarrow \left( \begin{array}{c|c|c} A_{00} & A_{01} & A_{02} \\ \hline A_{10} & A_{11} & A_{12} \\ \hline A_{20} & A_{21} & A_{22} \end{array} \right)$$

**endwhile**

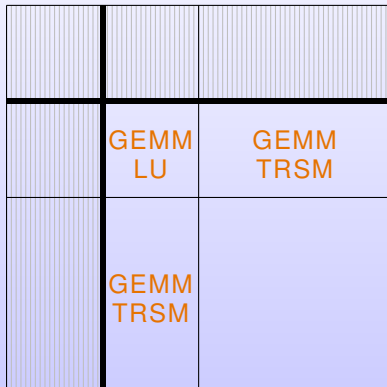
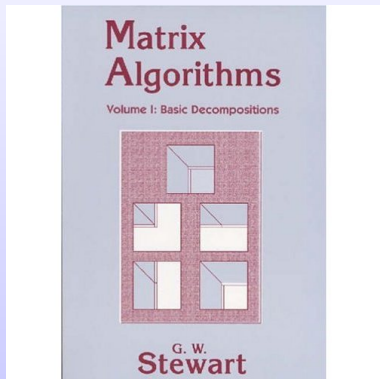
# Example: LU factorization

Iteration i: completed



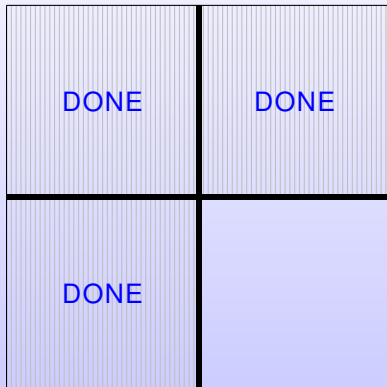
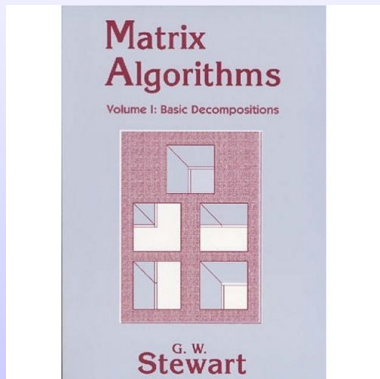
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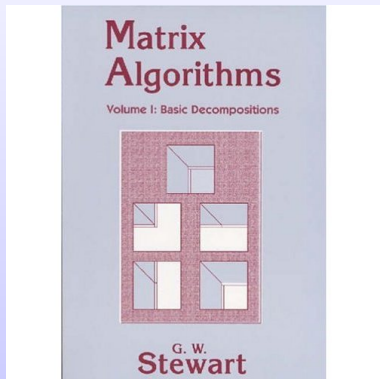
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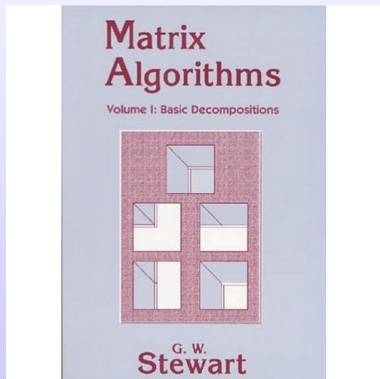
Iteration  $i+1$ : completed (boundary shift)





PME( $LU = A$ )

$$\left( \begin{array}{c|c} L_{TL}U_{TL} = A_{TL} & U_{TR} = L_{TL}^{-1}A_{TR} \\ \hline L_{BL} = A_{BL}U_{TL}^{-1} & L_{BR}U_{BR} = \\ & A_{BR} - L_{BL}U_{TR} \end{array} \right)$$



Loop-Invariant

$$\left( \begin{array}{c|c} L_{TL}U_{TL} = A_{TL} & U_{TR} = L_{TL}^{-1}A_{TR} \\ \hline L_{BL} = A_{BL}U_{TL}^{-1} & \end{array} \right)$$



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$$A_{01} := L_{00}^{-1} A_{01}$$

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$$A_{11} := LU(A_{11} - A_{10} A_{01})$$

**Continue**

$$\left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right) \leftarrow \left( \begin{array}{c|c|c} A_{00} & A_{01} & A_{02} \\ \hline A_{10} & A_{11} & A_{12} \\ \hline A_{20} & A_{21} & A_{22} \end{array} \right)$$

**endwhile**

Step	
1a	{ Precondition }
4	<b>Partition</b> ... <b>where</b> ...
2	{ Loop-Inv }
3	<b>While</b> $G$ <b>do</b>
2, 3	{ ( Loop-Inv ) $\wedge$ ( $G$ ) }
5a	<b>Repartition</b> ... <b>where</b> ...
6	{ LI-Before }
8	<i>Updates</i>
7	{ LI-After }
5b	<b>Continue with</b> ...
2	{ Loop-Inv }
	<b>endwhile</b>
2, 3	{ ( Loop-Inv ) $\wedge$ $\neg$ ( $G$ ) }
1b	{ Postcondition }

Step	$LU$
1a	$\{ A, L, U \in \mathbb{R}^{n \times n}, \text{ LowerTriUni}(L), \text{ UpperTri}(U) \}$
4	<b>Partition</b> $A, L, U$ <b>where ...</b>
2	$\{ L_{TL}U_{TL} = A_{TL} \}$
3	<b>While</b> $\text{size}(A_{TL}) < \text{size}(A)$ <b>do</b>
2,3	$\{ ( L_{TL}U_{TL} = A_{TL} ) \wedge ( \text{size}(A_{TL}) < \text{size}(A) ) \}$
5a	<b>Repartition</b>  $\rightarrow$  <b>where ...</b>
6	$\{ \text{LI-Before} \}$
8	$A_{01} := L_{00}^{-1}A_{01}$ $A_{10} := A_{10}U_{00}^{-1}$ $A_{11} := \text{LU}(A_{11} - A_{10}A_{01})$
7	$\{ \text{LI-After} \}$
5b	<b>Continue with</b>  $\leftarrow$ 
2	$\{ L_{TL}U_{TL} = A_{TL} \}$
	<b>endwhile</b>
2,3	$\{ ( L_{TL}U_{TL} = A_{TL} ) \wedge \neg ( \text{size}(A_{TL}) < \text{size}(A) ) \}$
1b	$\{ LU = A \}$

$$LU = A \quad \Rightarrow \quad \check{L}\check{U} = A + \Delta A$$

Operation	Analysis	Step
<b>Partition</b> Operands, Error Operands where ...		4
{ Loop-Invariant }	{ Error-Invariant }	2
<b>While</b> $G$ <b>do</b>		3
{ Loop-Invariant }	{ Error-Invariant }	2,3
<b>Repartition</b> Operands, Error Operands where ...		5a
{ LI-Before }	{ Err-Before }	6
<i>Updates</i>	<i>Error Updates</i>	8
{ LI-After }	{ Err-After }	7
<b>Continue with</b> ...		5b
{ Loop-Invariant }	{ Error-Invariant }	2
<b>endwhile</b>		

- 1 Motivation
- 2 Formal Derivation Techniques
- 3 Loop-Invariants
- 4 Worksheet
- 5 Analyses**
- 6 Blocked LU

**Partition**  $L \rightarrow \left( \begin{array}{c|c} L_{TL} & 0 \\ \hline L_{BL} & L_{BR} \end{array} \right), x \rightarrow \begin{pmatrix} x_T \\ x_B \end{pmatrix}, b \rightarrow \begin{pmatrix} b_T \\ b_B \end{pmatrix}$

where  $L_{TL}$  is  $0 \times 0$

**While**  $\text{size}(L_{TL}) < \text{size}(L)$  **do**

**Repartition**

$$\left( \begin{array}{c|c} L_{TL} & 0 \\ \hline L_{BL} & L_{BR} \end{array} \right) \rightarrow \left( \begin{array}{c|c|c} L_{00} & 0 & 0 \\ \hline l_{10}^T & \lambda_{11} & 0 \\ \hline L_{20} & l_{21} & L_{22} \end{array} \right), \begin{pmatrix} x_T \\ x_B \end{pmatrix} \rightarrow \begin{pmatrix} x_0 \\ \chi_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} b_T \\ b_B \end{pmatrix} \rightarrow \begin{pmatrix} b_0 \\ \beta_1 \\ b_2 \end{pmatrix}$$

---


$$\chi_1 := (\beta_1 - l_{10}^T x_0) / \lambda_{11}$$


---

**Continue**

$$\left( \begin{array}{c|c} L_{TL} & 0 \\ \hline L_{BL} & L_{BR} \end{array} \right) \leftarrow \left( \begin{array}{c|c|c} L_{00} & 0 & 0 \\ \hline l_{10}^T & \lambda_{11} & 0 \\ \hline L_{20} & l_{21} & L_{22} \end{array} \right), \begin{pmatrix} x_T \\ x_B \end{pmatrix} \leftarrow \begin{pmatrix} x_0 \\ \chi_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} b_T \\ b_B \end{pmatrix} \leftarrow \begin{pmatrix} b_0 \\ \beta_1 \\ b_2 \end{pmatrix}$$

**endwhile**

## Questions

- $(L + \Delta L)\check{x} = b$  ?  $(L + \Delta L)\check{x} = (b + \delta b)$  ?
- $|\Delta L| \leq O(n)\mathbf{u}|L|$  ?

**Partition**  $L \rightarrow \left( \begin{array}{c|c} L_{TL} & 0 \\ \hline L_{BL} & L_{BR} \end{array} \right), x \rightarrow \begin{pmatrix} x_T \\ x_B \end{pmatrix}, b \rightarrow \begin{pmatrix} b_T \\ b_B \end{pmatrix}$   
 where  $L_{TL}$  is  $0 \times 0$

**While**  $size(L_{TL}) < size(L)$  **do**

**Repartition**

$$\left( \begin{array}{c|c} L_{TL} & 0 \\ \hline L_{BL} & L_{BR} \end{array} \right) \rightarrow \left( \begin{array}{c|c|c} L_{00} & 0 & 0 \\ \hline l_{10}^T & \lambda_{11} & 0 \\ \hline L_{20} & l_{21} & L_{22} \end{array} \right), \begin{pmatrix} x_T \\ x_B \end{pmatrix} \rightarrow \begin{pmatrix} x_0 \\ \chi_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} b_T \\ b_B \end{pmatrix} \rightarrow \begin{pmatrix} b_0 \\ \beta_1 \\ b_2 \end{pmatrix}$$


---


$$\chi_1 := (\beta_1 - l_{10}^T x_0) / \lambda_{11}$$


---

**Continue**

$$\left( \begin{array}{c|c} L_{TL} & 0 \\ \hline L_{BL} & L_{BR} \end{array} \right) \leftarrow \left( \begin{array}{c|c|c} L_{00} & 0 & 0 \\ \hline l_{10}^T & \lambda_{11} & 0 \\ \hline L_{20} & l_{21} & L_{22} \end{array} \right), \begin{pmatrix} x_T \\ x_B \end{pmatrix} \leftarrow \begin{pmatrix} x_0 \\ \chi_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} b_T \\ b_B \end{pmatrix} \leftarrow \begin{pmatrix} b_0 \\ \beta_1 \\ b_2 \end{pmatrix}$$

**endwhile**

## Invariants?

- Loop-invariant:  $L_{TL}x_T = b_T$
- Error-invariant:  $(L_{TL} + \Delta L_{TL})\check{x}_T = b_T$

$Lx = b$	$(L + \Delta L)\tilde{x} = b$	Step
<b>Partition</b> $L \rightarrow \left( \begin{array}{c c} L_{TL} & 0 \\ \hline L_{BL} & L_{BR} \end{array} \right), x \rightarrow \begin{pmatrix} x_T \\ x_B \end{pmatrix}, b \rightarrow \begin{pmatrix} b_T \\ b_B \end{pmatrix},$ <b>where</b> $L_{TL}, \Delta L_{TL}$ are $0 \times 0$	$\Delta L \rightarrow \left( \begin{array}{c c} \Delta L_{TL} & 0 \\ \hline \Delta L_{BL} & \Delta L_{BR} \end{array} \right)$	4
	$\{ (L_{TL} + \Delta L_{TL})\tilde{x}_T = b_T \}$	2
<b>While</b> $size(L_{TL}) < size(L)$ <b>do</b>		3
	$\{ (L_{TL} + \Delta L_{TL})\tilde{x}_T = b_T \}$	2,3
<b>Repartition</b>		
$\dots, \left( \begin{array}{c c} \Delta L_{TL} & 0 \\ \hline \Delta L_{BL} & \Delta L_{BR} \end{array} \right) \rightarrow \left( \begin{array}{c c c} \Delta L_{00} & 0 & 0 \\ \hline \delta_{10}^T & \delta_{11} & 0 \\ \hline \Delta L_{20} & \delta_{21} & \Delta L_{22} \end{array} \right)$		5a
	$\{ (L_{00} + \Delta L_{00})\tilde{x}_0 = b_0 \}$	6
$\chi_1 := (\beta_1 - l_{10}^T x_0) / \lambda_{11}$	<i>Error Updates</i>	8
	$\left\{ \left( \begin{array}{c} (L_{00} + \Delta L_{00})\tilde{x}_0 = b_0 \\ \hline (l_{10}^T + \delta_{10}^T)\tilde{x}_0 + (\lambda_{11} + \delta_{11})\tilde{\chi}_1 = \beta_1 \end{array} \right) \right\}$	7
<b>Continue with</b>		
$\dots, \left( \begin{array}{c c} \Delta L_{TL} & 0 \\ \hline \Delta L_{BL} & \Delta L_{BR} \end{array} \right) \leftarrow \left( \begin{array}{c c c} \Delta L_{00} & 0 & 0 \\ \hline \delta_{10}^T & \delta_{11} & 0 \\ \hline \Delta L_{20} & \delta_{21} & \Delta L_{22} \end{array} \right)$		5b
	$\{ (L_{TL} + \Delta L_{TL})\tilde{x}_T = b_T \}$	2
<b>endwhile</b>		



Current status:  $(L_{00} + \Delta L_{00})\check{x}_0 = b_0$

Computation:  $\chi_1 := (\beta_1 - l_{10}^T x_0) / \lambda_{11}$

After: 
$$\left( \begin{array}{l} (L_{00} + \Delta L_{00})\check{x}_0 = b_0 \\ \hline (l_{10}^T + \delta l_{10}^T)\check{x}_0 + (\lambda_{11} + \delta \lambda_{11})\check{\chi}_1 = \beta_1 \end{array} \right)$$

## Sub-goal

Can the error generated by  $\chi_1 := (\beta_1 - l_{10}^T x_0) / \lambda_{11}$  be accumulated into  $\delta l_{10}^T$  and  $\delta \lambda_{11}$ ?

$$\nu := (\beta - l^T x) / \lambda, \quad \beta, \lambda \in \mathbb{R}, \quad l, y \in \mathbb{R}^n$$

## Computational models

- $[\chi \text{ op } \psi] = (\chi \text{ op } \psi)(1 + \epsilon), \quad |\epsilon| \leq \mathbf{u}, \text{ and } \text{op} \in \{+, -, *, /\}$
- $[\chi \text{ op } \psi] = \frac{\chi \text{ op } \psi}{1 + \epsilon}, \quad |\epsilon| \leq \mathbf{u}, \text{ and } \text{op} \in \{+, -, *, /\}$

$$1: \lambda \check{\nu} = (\beta + \delta\beta) - (l + \delta l)^T x \quad \begin{cases} |\delta\beta| \leq \gamma_2 |\beta| \\ |\delta l| \leq \gamma_{n+2} |l| \end{cases}$$

$$2: (\lambda + \delta\lambda) \check{\nu} = \beta - (l + \delta l)^T x \quad \begin{cases} |\delta\lambda| \leq \gamma_2 |\lambda| \\ |\delta l| \leq \gamma_n |l| \end{cases}$$

$$3: (\lambda + \delta\lambda) \check{\nu} = (\beta + \delta\beta) - (l + \delta l)^T x \quad \begin{cases} |\delta\beta| \leq \gamma_1 |\beta| \\ |\delta l| \leq \gamma_{n+1} |l| \\ |\delta\lambda| \leq \gamma_1 |\lambda| \end{cases}$$

$$\nu := (\beta - l^T x) / \lambda, \quad \beta, \lambda \in \mathbb{R}, \quad l, y \in \mathbb{R}^n$$

## Computational models

- $[\chi \text{ op } \psi] = (\chi \text{ op } \psi)(1 + \epsilon), \quad |\epsilon| \leq \mathbf{u}, \text{ and } \text{op} \in \{+, -, *, /\}$
- $[\chi \text{ op } \psi] = \frac{\chi \text{ op } \psi}{1 + \epsilon}, \quad |\epsilon| \leq \mathbf{u}, \text{ and } \text{op} \in \{+, -, *, /\}$

$$1: \lambda \check{\nu} = (\beta + \delta\beta) - (l + \delta l)^T x \quad \begin{cases} |\delta\beta| \leq \gamma_2 |\beta| \\ |\delta l| \leq \gamma_{n+2} |l| \end{cases}$$

$$2: (\lambda + \delta\lambda) \check{\nu} = \beta - (l + \delta l)^T x \quad \begin{cases} |\delta\lambda| \leq \gamma_2 |\lambda| \\ |\delta l| \leq \gamma_n |l| \end{cases}$$

$$3: (\lambda + \delta\lambda) \check{\nu} = (\beta + \delta\beta) - (l + \delta l)^T x \quad \begin{cases} |\delta\beta| \leq \gamma_1 |\beta| \\ |\delta l| \leq \gamma_{n+1} |l| \\ |\delta\lambda| \leq \gamma_1 |\lambda| \end{cases}$$

$Lx = b$	$(L + \Delta L)\tilde{x} = b$	Step
<b>Partition</b> $L, x, b, \Delta L$		4
	$\{ (L_{TL} + \Delta L_{TL})\tilde{x}_T = b_T \}$	2
<b>While</b> $size(L_{TL}) < size(L)$ <b>do</b>		3
	$\{ (L_{TL} + \Delta L_{TL})\tilde{x}_T = b_T \}$	2,3
<b>Repartition</b>		5a
$\chi_1 := (\beta_1 - l_{10}^T x_0) / \lambda_{11}$   $\beta_1 = (l_{10}^T + \delta_{10}^T) \tilde{x}_0 + (\lambda_{11} + \delta_{11}) \tilde{\chi}_1$ $\wedge  (\delta_{10}^T   \delta_{11})  \leq \max(\gamma_2, \gamma_k)  (l_{10}^T   \lambda_{11}) $		8
<b>Continue with</b>		5b
	$\{ (L_{TL} + \Delta L_{TL})\tilde{x}_T = b_T \}$	2
<b>endwhile</b>		

On exit:

- $(L_{TL} + \Delta L_{TL})\tilde{x}_T = b_T \quad \wedge \quad size(L_{TL}) = size(L) \implies (L + \Delta L)\tilde{x} = b$
- $|\Delta L| \leq \max(\gamma_2, \gamma_{n-1}) |L|$

**Partition**  $A \rightarrow \left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right)$

where  $A_{TL}$  is  $0 \times 0$

**While**  $size(A_{TL}) < size(A)$  **do**

**Repartition**

$$\left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right) \rightarrow \left( \begin{array}{c|c|c} A_{00} & a_{01} & A_{02} \\ \hline a_{10}^T & \alpha_{11} & a_{12}^T \\ \hline A_{20} & a_{21} & A_{22} \end{array} \right)$$

$$\alpha_{11} := \alpha_{11} - a_{10}^T a_{01}$$

$$a_{21} := (a_{21} - A_{20} a_{01}) / \alpha_{11}$$

$$a_{12}^T := (a_{12}^T - a_{10}^T A_{02})$$

**Continue**

$$\left( \begin{array}{c|c} A_{TL} & A_{TR} \\ \hline A_{BL} & A_{BR} \end{array} \right) \leftarrow \left( \begin{array}{c|c|c} A_{00} & a_{01} & A_{02} \\ \hline a_{10}^T & \alpha_{11} & a_{12}^T \\ \hline A_{20} & a_{21} & A_{22} \end{array} \right)$$

**endwhile**

## Questions

- $\check{L}\check{U} = A + \Delta A$  ?
- $|\Delta A| \leq O(n)\mathbf{u}|\check{L}||\check{U}|$  ?  
 $|\Delta A| \leq O(n)\mathbf{u}(|\check{L}||\check{U}| + |A|)$  ?

## Invariants

- **Loop-invariant:**

$$\left( \begin{array}{c|c} L_{TL}U_{TL} = A_{TL} & L_{TL}U_{TR} = A_{TR} \\ \hline L_{BL}U_{TL} = A_{BL} & \end{array} \right)$$

- **Error-invariant:**

$$\left( \begin{array}{c|c} \check{L}_{TL}\check{U}_{TL} = A_{TL} + \Delta A_{TL} & \check{L}_{TL}\check{U}_{TR} = A_{TR} + \Delta A_{TR} \\ \hline \check{L}_{BL}\check{U}_{TL} = A_{BL} + \Delta A_{BL} & \end{array} \right)$$

$\left\{ \begin{array}{c c c} \left( \begin{array}{l} \check{L}_{00}\check{U}_{00} = A_{00} + \Delta A_{00} \\ \check{l}_{10}^T\check{U}_{00} = a_{10}^T + \delta a_{10}^T \\ \check{L}_{20}\check{U}_{00} = A_{20} + \Delta A_{20} \end{array} \right) & \begin{array}{l} \check{L}_{00}\check{u}_{01} = a_{01} + \delta a_{01} \\ -- \\ -- \end{array} & \begin{array}{l} \check{L}_{00}\check{U}_{02} = A_{02} + \Delta A_{02} \\ -- \\ -- \end{array} \end{array} \right\}$		
$v_{11} := \alpha_{11} - l_{10}^T u_{01}$ $u_{12}^T := a_{12}^T - l_{10}^T U_{02}$ $l_{21} := (a_{21} - L_{20}u_{01})/v_{11}$		<i>Error Updates</i>
$\left\{ \begin{array}{c c c} \left( \begin{array}{l} \check{L}_{00}\check{U}_{00} = A_{00} + \Delta A_{00} \\ \check{l}_{10}^T\check{U}_{00} = a_{10}^T + \delta a_{10}^T \\ \check{L}_{20}\check{U}_{00} = A_{20} + \Delta A_{20} \end{array} \right) & \begin{array}{l} \check{L}_{00}\check{u}_{01} = a_{01} + \delta a_{01} \\ \check{l}_{10}^T\check{u}_{01} + \check{v}_{11} = \alpha_{11} + \delta \alpha_{11} \\ \check{L}_{20}\check{u}_{01} + \check{l}_{21}\check{v}_{11} = a_{21} + \delta a_{21} \end{array} & \begin{array}{l} \check{L}_{00}\check{U}_{02} = A_{02} + \Delta A_{02} \\ \check{l}_{10}^T\check{U}_{02} + \check{u}_{12}^T = a_{12}^T + \delta a_{12}^T \\ -- \end{array} \end{array} \right\}$		

## Sub-goals

- $v_{11} := \alpha_{11} - l_{10}^T u_{01} \quad \stackrel{?}{\Rightarrow} \quad \check{l}_{10}^T \check{u}_{01} + \check{v}_{11} = \alpha_{11} + \delta \alpha_{11}$
- $u_{12}^T := a_{12}^T - l_{10}^T U_{02} \quad \stackrel{?}{\Rightarrow} \quad \check{l}_{10}^T \check{U}_{02} + \check{u}_{12}^T = a_{12}^T + \delta a_{12}^T$
- $l_{21} := (a_{21} - L_{20}u_{01})/v_{11} \quad \stackrel{?}{\Rightarrow} \quad \check{L}_{20}\check{u}_{01} + \check{l}_{21}\check{v}_{11} = a_{21} + \delta a_{21}$

- $v_{11} := \alpha_{11} - l_{10}^T u_{01}$

$$l_{10}^T u_{01} + \tilde{v}_{11} = \alpha_{11} + \delta v_{11}, \quad |\delta v_{11}| \leq \gamma_{k+1} \left( |l_{10}^T| |u_{01}| + |\tilde{v}_{11}| \right)$$

- $u_{12}^T := a_{12}^T - l_{10}^T U_{02}$

$$l_{10}^T U_{02} + \tilde{u}_{12}^T = a_{12}^T + \delta u_{12}^T, \quad |\delta u_{12}^T| \leq \gamma_{k+1} \left( |l_{10}^T| |U_{02}| + |\tilde{u}_{12}^T| \right)$$

- $l_{21} := (a_{21} - L_{20} u_{01}) / v_{11}$

$$L_{20} u_{01} + v_{11} \check{l}_{21} = a_{21} + \delta l_{21}, \quad |\delta l_{21}| \leq \gamma_{k+1} (|L_{20}| |u_{01}| + |\check{l}_{21}| |v_{11}|)$$

$$\Rightarrow \left( \begin{array}{c|c} \check{L}_{TL} \check{U}_{TL} = A_{TL} + \Delta A_{TL} & \check{L}_{TL} \check{U}_{TR} = A_{TR} + \Delta A_{TR} \\ \hline \check{L}_{BL} \check{U}_{TL} = A_{BL} + \Delta A_{BL} & \end{array} \right)$$

$$\Rightarrow \check{L} \check{U} = A + \Delta A, \quad |\Delta A| \leq \gamma_n |\check{L}| |\check{U}|$$

- Target operation:  $LU = A$
- Algorithm: LU, TRSM( $\times 2$ ), GEMM;
- Loop-invariant:

$$\left( \begin{array}{c|c} L_{TL}U_{TL} = A_{TL} & L_{TL}U_{TR} = A_{TR} \\ \hline L_{BL}U_{TL} = A_{BL} & A_{BR}^i = A_{BR} - L_{BL}U_{TR} \end{array} \right)$$



# Conclusions: blocked LU (sketch)

- Target operation:  $LU = A$
- Algorithm: LU, TRSM( $\times 2$ ), GEMM;
- Loop-invariant:

$$\left( \begin{array}{c|c} L_{TL}U_{TL} = A_{TL} & L_{TL}U_{TR} = A_{TR} \\ \hline L_{BL}U_{TL} = A_{BL} & A_{BR}^i = A_{BR} - L_{BL}U_{TR} \end{array} \right)$$

## Goal oriented

- Target analysis:  $\check{L}\check{U} = A + \Delta A$
- Target bounds:  $|\Delta A| \leq \gamma_n |\check{L}||\check{U}|$ ,  $|\Delta A| \leq \gamma_{\frac{n}{b}+b} (|\check{L}||\check{U}| + |A|)$
- Error-invariant:

$$\left( \begin{array}{c|c} \check{L}_{TL}\check{U}_{TL} = A_{TL} + \Delta A_{TL} & \check{L}_{TL}\check{U}_{TR} = A_{TR} + \Delta A_{TR} \\ \hline \check{L}_{BL}\check{U}_{TL} = A_{BL} + \Delta A_{BL} & \check{A}_{BR}^i = A_{BR} - \check{L}_{BL}\check{U}_{TR} + \Delta A_{BR}^i \end{array} \right) \wedge$$

$$\left| \left( \begin{array}{c|c} \Delta A_{TL} & \Delta A_{TR} \\ \hline \Delta A_{BL} & \Delta A_{BR}^i \end{array} \right) \right| \leq \gamma_{\frac{k}{b}+b} \left( \begin{array}{c|c} |A_{TL}| + |\check{L}_{TL}||\check{U}_{TL}| & |A_{TR}| + |\check{L}_{TL}||\check{U}_{TR}| \\ \hline |A_{BL}| + |\check{L}_{BL}||\check{U}_{TL}| & |A_{BR}| + |\check{L}_{BL}||\check{U}_{TR}| \end{array} \right) \wedge$$

$$\text{size}(A_{TL}) = k \times k$$

## Modular

Composition of analyses

Subgoals:

- Recursive  $LU_{11} \stackrel{?}{\Rightarrow} \text{target}_{11}$
- $TRSM_{12} \stackrel{?}{\Rightarrow} \text{target}_{12}$
- $TRSM_{21} \stackrel{?}{\Rightarrow} \text{target}_{21}$
- $GEMM_{22} \stackrel{?}{\Rightarrow} \text{target}_{22}$

## Systematic

Prescribed sequence of steps

Sylvester? Undergraduate project

- Robert van de Geijn
- The FLAME team
- “Goal-oriented and modular stability analysis” (SIMAX)  
Dedicated to Pete on the occasion of his 70th bday

Deutsche  
Forschungsgemeinschaft

**DFG**

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